



TERROVA® QUEST™

BOW-MOUNT TROLLING MOTOR

Owner's Manual

INTRODUCTION

THANK YOU

Thank you for choosing Minn Kota. We believe that you should spend more time fishing and less time positioning your boat. That's why we build the smartest, toughest, most intuitive trolling motors on the water. Every aspect of a Minn Kota trolling motor is thought out and rethought until it's good enough to bear our name. Countless hours of research and testing provide you the Minn Kota advantage that can truly take you "Anywhere. Anytime." We don't believe in shortcuts. We are Minn Kota. And we are never done helping you catch more fish.

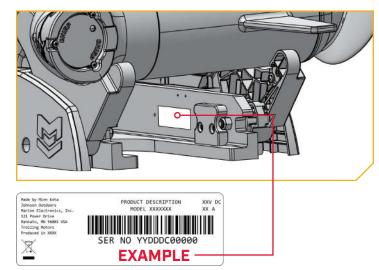
REGISTRATION

Remember to keep your receipt and immediately register your trolling motor on our website at minnkota.johnsonoutdoors.com/register.

SERIAL NUMBER

Your Minn Kota 11-character serial number is very important. It helps to determine the specific model and year of manufacture. When contacting Consumer Service or registering your product, you will need to know your product's serial number.

NOTICE: The serial number for the Terrova QUEST is located on the inside of the Mount, behind the left Fall Away Ramp.



MOTOR INFORMATION (For Consumer Reference Only)

Model:		
Serial Number:		
Purchase Date:		
Store Where Purchased:		

NOTICE: Do not return your Minn Kota motor to your retailer. Your retailer is not authorized to repair or replace this unit. You may obtain service by: calling Minn Kota at (800) 227-6433; returning your motor to the Minn Kota Factory Service Center; sending or taking your motor to any Minn Kota authorized service center. A list of authorized service centers is available on our website at minnkota.johnsonoutdoors.com. Please include proof of purchase, serial number and purchase date for warranty service with any of the above options.

Made for iPhone® 11 and iPhone X

For updated iOS, Humminbird® and Minn Kota® compatibility, visit minnkota.johnsonoutdoors.com





Use of the Made for Apple badge means that an accessory has been designed to connect specifically to the Apple product(s) identified in the badge, and has been certified by the developer to meet Apple performance standards. Apple is not responsible for the operation of this device or its compliance with safety and regulatory standards. iPhone is a trademark of Apple Inc., registered in the U.S. and other countries. The trademark "iPhone" is used in Japan with a license from Aiphone K.K.

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SAFETY CONSIDERATIONS

Please thoroughly read the user manual. Follow all instructions and heed all safety and cautionary notices. Use of this motor is only permitted for persons that have read and understood these user instructions. Minors may use this motor only under adult supervision.

⚠ WARNING

You are responsible for the safe and prudent operation of your vessel. We have designed your Minn Kota product to be an accurate and reliable tool that will enhance boat operation and improve your ability to catch fish. This product does not relieve you from the responsibility for safe operation of your boat. You must avoid hazards to navigation and always maintain a permanent watch so you can respond to situations as they develop. You must always be prepared to regain manual control of your boat. Learn to operate your Minn Kota product in an area free from hazards and obstacles.

⚠ WARNING

Never run the motor out of the water, as this may result in injuries from the rotating propeller. The motor should be disconnected from the power source when it is not in use or is off the water. When connecting the power-supply cables of the motor to the battery, ensure that they are not kinked or subject to chafe and route them in such a way that persons cannot trip over them. Before using the motor make sure that the insulation of the power cables is not damaged. Disregarding these safety precautions may result in electric shorts of battery(s) and/or motor. Always disconnect motor from battery(s) before cleaning or checking the propeller. Avoid submerging the complete motor as water may enter the lower unit through control head and shaft. If the motor is used while water is present in the lower unit considerable damage to the motor can occur. This damage will not be covered by warranty.

▲ WARNING

Take care that neither you nor other persons approach the turning propeller too closely, neither with body parts nor with objects. The motor is powerful and may endanger or injure you or others. While the motor is running watch out for persons swimming and for floating objects. Persons whose ability to run the motor or whose reactions are impaired by alcohol, drugs, medication, or other substances are not permitted to use this motor. This motor is not suitable for use in strong currents. The constant noise pressure level of the motor during use is less than 70dB(A). The overall vibration level does not exceed 2,5 m/sec2.

⚠ WARNING

When stowing or deploying the motor, keep fingers clear of all hinge and pivot points and all moving parts. In the event of unexpected operation, remove power leads from the battery.

▲ WARNING

It is recommended to only use Johnson Outdoors approved accessories with your Minn Kota motor. Using non-approved accessories including to mount or control your motor may cause damage, unexpected motor operation and injury. Be sure to use the product and approved accessories, including remotes, safely and in the manner directed to avoid accidental or unexpected motor operation. Keep all factory installed parts in place including motor and accessory covers, enclosures and guards.

WARRANTY

WARRANTY ON MINN KOTA FRESHWATER TROLLING MOTORS

Minn Kota Freshwater Trolling Motors - Limited Lifetime Warranty On Composite Shaft And Limited Two-Year Warranty On The Entire Product

Johnson Outdoors Marine Electronics, Inc. ("JOME") extends the following limited warranty to the original retail purchaser only. Warranty coverage is not transferable.

Minn Kota Limited Two-Year Warranty on the Entire Product

JOME warrants to the original retail purchaser only that the purchaser's new Minn Kota freshwater trolling motor will be materially free from defects in materials and workmanship appearing within two (2) years after the date of purchase. JOME will (at its option) either repair or replace, free of charge, any parts found by JOME to be defective during the term of this warranty. Such repair, or replacement shall be the sole and exclusive liability of JOME and the sole and exclusive remedy of the purchaser for breach of this warranty.

Minn Kota Limited Lifetime Warranty on the Composite Shaft

JOME warrants to the original retail purchaser only that the composite shaft of the purchaser's Minn Kota trolling motor will be materially free from defects in materials and workmanship appearing within the original purchaser's lifetime. JOME will provide a new composite shaft, free of charge, to replace any composite shaft found by JOME to be defective during the term of this warranty. Providing a new composite shaft shall be the sole and exclusive liability of JOME and the sole and exclusive remedy of the purchaser for breach of this warranty; and purchaser shall be responsible for installing, or for the cost of labor to install, any new composite shaft provided by JOME.

Exclusions and Limitations

This limited warranty does not apply to products that have been used in saltwater or brackish water, commercially or for rental purposes. This limited warranty does not cover normal wear and tear, blemishes that do not affect the operation of the product, or damage caused by accidents, abuse, alteration, modification, shipping damages, acts of God, negligence of the user or misuse, improper or insufficient care or maintenance. DAMAGE CAUSED BY THE USE OF OTHER REPLACEMENT PARTS NOT MEETING THE DESIGN SPECIFICATIONS OF THE ORIGINAL PARTS WILL NOT BE COVERED BY THIS LIMITED WARRANTY. The cost of normal maintenance or replacement parts which are not in breach of the limited warranty are the responsibility of the purchaser. Prior to using products, the purchaser shall determine the suitability of the products for the intended use and assumes all related risk and liability. Any assistance JOME provides to or procures for the purchaser outside the terms, limitations or exclusions of this limited warranty will not constitute a waiver of the terms, limitations or exclusions, nor will such assistance extend or revive the warranty. JOME will not reimburse the purchaser for any expenses incurred by the purchaser in repairing, correcting or replacing any defective products or parts, except those incurred with JOME's prior written permission. JOME'S AGGREGATE LIABILITY WITH RESPECT TO COVERED PRODUCTS IS LIMITED TO AN AMOUNT EQUAL TO THE PURCHASER'S ORIGINAL PURCHASE PRICE PAID FOR SUCH PRODUCT.

Minn Kota Service Information

To obtain warranty service in the U.S., the product believed to be defective, and proof of original purchase (including the date of purchase), must be presented to a Minn Kota Authorized Service Center. Go to minnkota.johnsonoutdoors.com/us/support/service-providers/locate to find a Minn Kota Authorized Service Center. Any charges incurred for service calls, transportation or shipping/freight to/from the Minn Kota Authorized Service Center, labor to haul out, remove, re-install or re-rig products removed for warranty service, or any other similar items are the sole and exclusive responsibility of the purchaser. Products purchased outside of the U.S. must be returned prepaid with proof of purchase (including the date of purchase and serial number) to any Authorized Minn Kota Service Center in the country of purchase. To contact Minn Kota Customer Service go to minnkota-help.johnsonoutdoors.com/hc/en-us. Products repaired or replaced will be warranted for the remainder of the original warranty period, or for 90 days from the date of repair or replacement, whichever is longer. For any product that is returned for warranty service that JOME finds to be not covered by or not in breach of this limited warranty, there will be a billing for services rendered at the prevailing labor rate of the applicable Minn Kota Authorized Service Center and for a minimum of at least one hour.



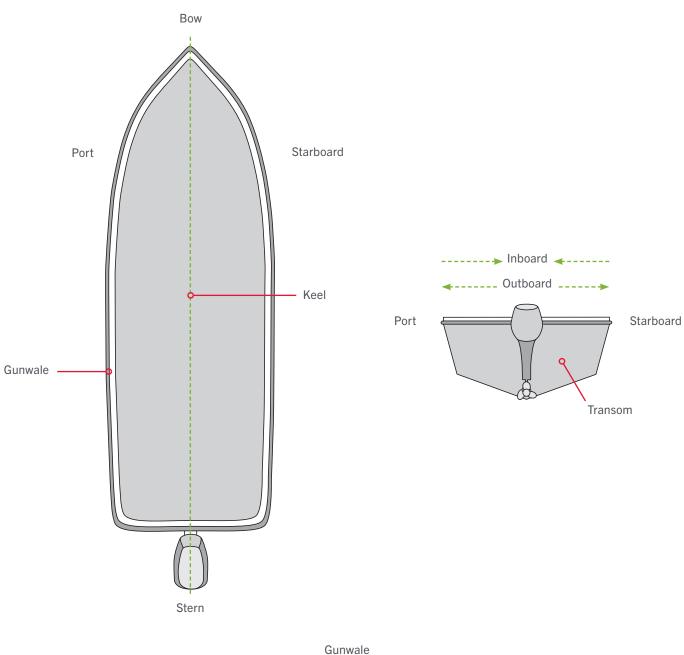


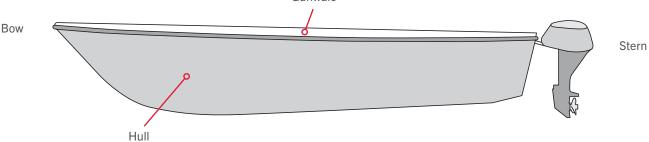
NOTICE: Do not return your Minn Kota product to your retailer. Your retailer is not authorized to repair or replace products.

NOTICE: THERE ARE NO EXPRESS WARRANTIES OTHER THAN THESE LIMITED WARRANTIES. IN NO EVENT SHALL ANY IMPLIED WARRANTIES INCLUDING ANY IMPLIED WARRANTIES OF MERCHANTABILITY OR FITNESS FOR PARTICULAR PURPOSE, EXTEND BEYOND THE DURATION OF THE RELEVANT EXPRESS LIMITED WARRANTY. IN NO EVENT SHALL JOME BE LIABLE FOR PUNITIVE, INDIRECT, INCIDENTAL, CONSEQUENTIAL OR SPECIAL DAMAGES. Without limiting the foregoing, JOME assumes no responsibility for loss of use of product, loss of time, inconvenience or other damage.

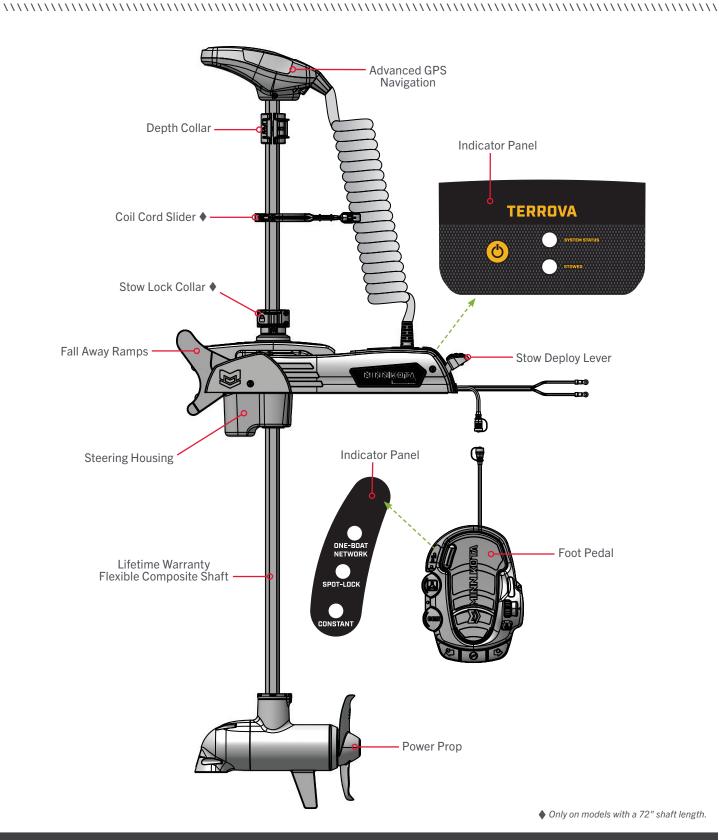
Some states do not allow limitations on how long an implied warranty lasts or the exclusion or limitation of incidental or consequential damages, so the above limitations and/or exclusions may not apply to you. This warranty gives you specific legal rights and you may also have other legal rights which vary from state to state.

KNOW YOUR BOAT





FEATURES



NOTICE: Specifications subject to change without notice. This diagram is for reference only and may differ from your actual motor.

INSTALLATION

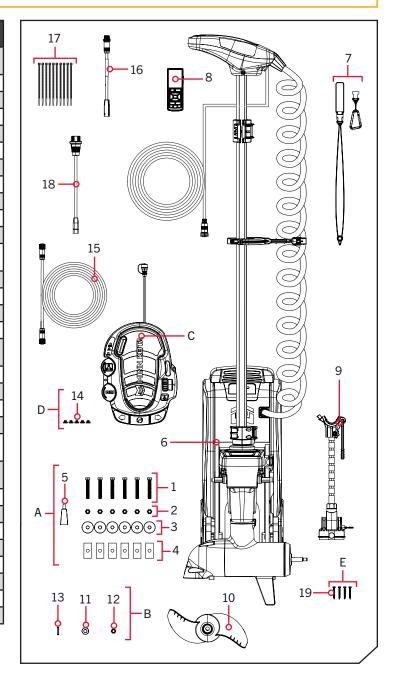
INSTALLING THE TERROVA QUEST

Your new Terrova QUEST comes with everything you'll need to install it directly to the boat. The motor can be mounted directly to the bow or coupled with a Minn Kota quick release bracket for ease of mounting and removal. For compatible quick release brackets and to locate your nearest dealer, visit minnkota.johnsonoutdoors.com. To install the motor directly to the boat, follow the instructions provided in this manual. Please review the parts list, mounting considerations and tools needed for installation prior to getting started. For additional product support, visit minnkota.johnsonoutdoors.com.

INSTALLATION PARTS LIST >

Item / Assembly	Part #	Description	Qty.
A (Includes 1-5)	2994948	BAG ASM, INSTINCT, T3 BL HDW	1
1	2323440	SCREW-3/8-16 X 2 1/2 HHCS SS	6
2	2383122	NUT 3/8-16 NYLON INST LOCKNUT	6
3	2321710	WASHER, RUBBER MOUNT	6
4	2371796	BACKUP BAR 3/16 X 1 X 2	6
5	2378608	ANTI SEIZE TUBE, 4CC, TALON	1
6	×	MOTOR ASSEMBLY	1
7	2390802	LANYARD w/CARARBINER IP RMT U2	1
8	411690-1	TROLLING MOTOR REMOTE	1
9	2992371	STABILIZER, BWMT ES TM ASM *72"*	1
10	2321170	PROP, POWER REAMED	1
B (Includes 11-13)	2992604	BAG ASSM, PROP HARDWARE	1
11	2091701	WASHER-PROP (LARGE) MAX101	1
12	2093101	NUT-PROP,NYLOC,LG,MX101 3/8 SS	1
13	2262659	PIN-DRIVE 1" X 3/16 SS 17-4	1
С	2994735	FOOT PEDAL ASM, TRV 3 BL	1
D (Includes 14)	2994859	BAG ASY-TERROVA/V2,RUB.BUMPERS	1
14	2325110	PAD,FOOT PEDAL PD	5
15	490384-4	CABLE, ETHERNET (M12-M12), 30'	1
16	490380-1	CABLE, ETHERNET PIGTAIL-700 HD	1
17	2996300	BAG ASM, TIE WRAPS, LOW PRO 4"	1
18	2994961	BAG ASM, CABLE, ADPTR, 490537-2 *490537-2* *MKR-MI-1* *DSC* *MSI*	1
E (Includes 19)	2994955	BAG ASM, MKA-60 STABILIZER *72"*	1
19	2383475	SCREW-#8-18x1½L SELF DRILL SS *72"*	4
A	2327138	MANUAL, TERROVA 3 BL	1
A	2327140	MANUAL-INSTLL GUIDE T3 BL	1
A	2397110	MANUAL, WIRELESS REMOTE	1
A	2397115	GUIDE-QCK REFERENCE iP 4.0	1
A	2294950	INSTRUCTIONS,OBN & REMOTE PAIR	1
A	2207130	BRUSHLESS QS SETUP GUIDE	1
A	2377179	INSTR.SHEET, MKA-60 STBLZR *72"*	1

- ▲ Not shown on Parts Diagram.
- * This part is included in an assembly and cannot be ordered individually.



MOUNTING CONSIDERATIONS

MOUNTING CONSIDERATIONS >

It is recommended that the motor be mounted as close to the centerline or keel of the boat as possible. Make sure the area under the mounting location is clear to drill holes and install hardware. The mounting surface for the Terrova QUEST must be flat. Rubber washers can be used to shim the base extrusion flat before hardware is tightened.

The motor must not encounter any obstructions as it is lowered into the water or raised into the boat when stowed and deployed. When stowed, ensure that there is enough room for the Shaft and Control Head and that they do not extend off the side of the boat.



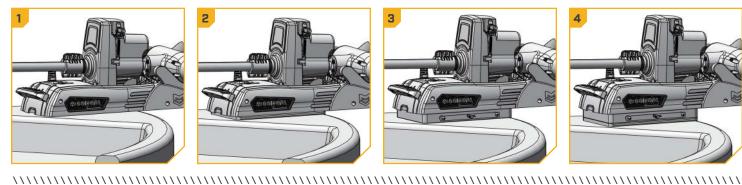
View accessories available for your trolling motor at minnkota. johnsonoutdoors.com.

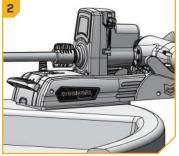
All six mounting holes must be used when securing the Terrova QUEST to the boat deck. If the desired mounting location does not allow for all six mounting holes and mounting bolts, a Boat Deck Reinforcement Kit (1854058) should be used or a new mounting location selected. Consider a quick release bracket with the installation of your motor.

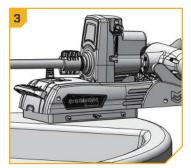
Mounting options for the Terrova QUEST include:

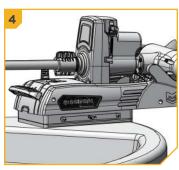
- 1. Installing the motor directly to the boat deck
- 2. Mounting the motor with an MKA-58 Boat Deck Reinforcement Kit (1854058)
- 3. Mounting the motor with an MKA-56/RTA-55 composite quick release bracket (1854056 black/1854055 white) or an MKA-57 sliding quick release bracket (1854057)
- 4. Combining an MKA-58 Boat Deck Reinforcement Kit and an MKA-56/RTA-55 Quick Release Bracket with the Terrova QUEST

When mounting the Terrova QUEST directly to the boat, follow the installation instructions outlined in this manual. If an accessory bracket will be used to mount the Terrova QUEST, follow the installation instructions provided with the mounting accessory. To view a list of compatible accessories, visit minnkota.johnsonoutdoors.com.









TOOLS AND RESOURCES REQUIRED >

- #3 Phillips Screwdriver
- Drill
- 3/8" Drill Bit

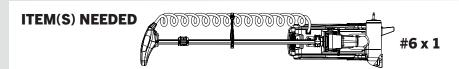
- Needle-nose Pliers
- Awl or similar marking tool
- 9/16" Open/Box End Wrench

- 9/16" Deep Well Socket
- · A second person to help with the installation

INSTALLATION >

INSTALLING THE TERROVA QUEST

1



1a

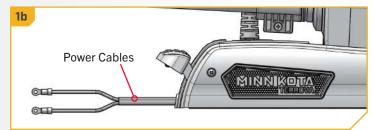
- a. Place the trolling motor (Item #6) on an elevated, level surface, such as a workbench or the tailgate of a pickup. The motor, as removed from the box, should be in the stowed position.
- b. Make sure that the Power Cables from the battery are disconnected or that the breaker, if equipped, is "off."



△ WARNING

Make sure the motor is on a level surface and is not connected to a power source.

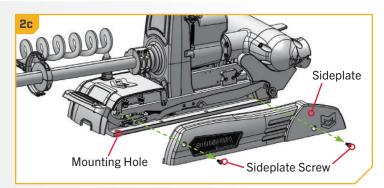
NOTICE: The trolling motor weighs up to 90lb. Minn Kota recommends having a second person help with the installation.



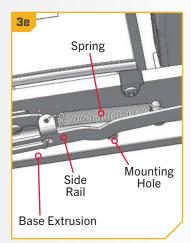
2

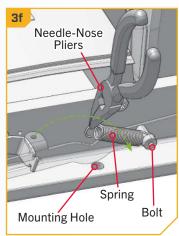
- c. Remove the four Sideplate Screws using a #3 Phillips Screwdriver. Two screws will be located on each side of the mount.
- d. Remove the Right Sideplate and Left Sideplate to expose the six mounting holes in the Base Extrusion.

NOTICE: Ensure that the area between the Mount and Steering Housing is clean and free of debris and that no installation hardware has fallen in. The Mount contains pads that contact the Steering Housing when stowed. The motor cannot stow securely if an obstruction is present on the pads.



- The center mounting hole on each side of the Base Extrusion is blocked by a Spring. One end of each Spring must be disconnected in order to access the mounting holes.
- f. To disconnect the Spring, take a Needle-nose Pliers and carefully grab the hooked end on the top half of the Spring. Unhook it from the hole in the Side Rail by pulling up and away. Guide it towards the bottom half of the Spring still attached to the Base Extrusion and gently set it down. Do not disconnect the end of the Spring that is wrapped around a bolt. Repeat this process with the remaining Spring on the other side of the mount.





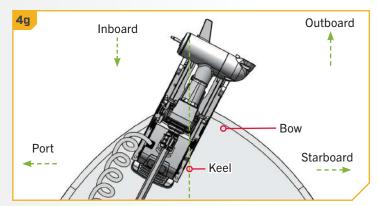
CAUTION

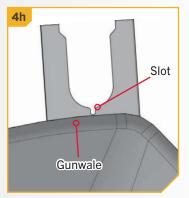
When maneuvering each Spring, carefully handle the Spring to avoid bending it. Do not grab the body of the Spring to avoid pinching between the spring coils. Always grab by the hooked end.

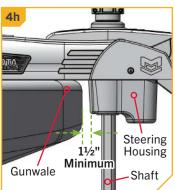
△ CAUTION

When handling each Spring, always keep the spring tension under control. Abruptly releasing the Spring while there is still tension could damage it and cause it to release unpredictably.

- Review the mounting considerations at the beginning of the Installation section for proper clearance. Place the motor on the bow of the boat at the intended mounting location, as close to the centerline or keel as possible. Ensure there is enough room for the Shaft and Control Head and that they do not extend off the side of the boat. The motor can be installed on either the Port or Starboard side of the bow. based on personal preference.
- h. Position the motor so that the Slot in the Base Extrusion is positioned beyond the boat Gunwale. For proper clearance, the entire Slot must be visible beyond the Gunwale. When the motor is deployed, there must be a minimum required distance of 11/2" between the Gunwale and the bottom of the Steering Housing and Shaft.
- When mounting the Terrova QUEST, all six mounting holes must be used. If the desired mounting location does not allow for all six mounting holes, a Boat Deck Reinforcement Kit (1854058) should be used or a new mounting location selected.



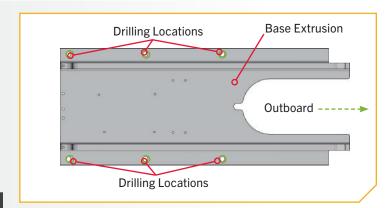




5

- j. With the motor at the intended mounting location, take an Awl or similar tool and mark all six mounting holes in the Base Extrusion.
- k. Slide the motor aside to drill the mounting holes.
- I. Drill through the boat deck using a Drill and a 3/8" Drill Bit on all six marked locations.
- m. Reposition the motor over the drilled holes to install mounting hardware.

NOTICE: New mounting holes are required when upgrading from a Terrova to a Terrova QUEST. New mounting holes will accommodate the higher thrust motor and ensure the installation is secure.



NOTICE: The mounting surface for the Terrova QUEST must be flat. Rubber Washers can be used to shim the Base Extrusion flat before hardware is tightened.

6

ITEM(S) NEEDED

#1 x 6

© #2 x 6

(°)#3 x 6

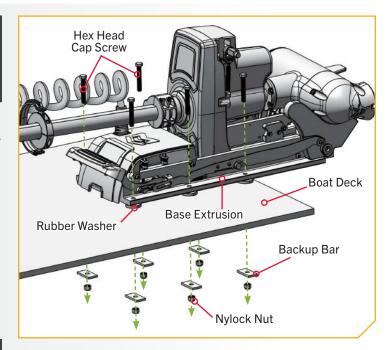
○ #4 x 6

#5 x 1

NOTICE: To prevent seizing of the stainless steel hardware, do not use high-speed installation tools. Wetting the screws or applying an anti-seize (Item #5) may help prevent seizing.

- n. Take six Hex Head Cap Screws (Item #1) and apply anti-seize (Item #5) to each Screw. Insert the Screws through the Base Extrusion and into each of the drilled locations. If Rubber Washers (Item #3) are used, the Rubber Washers should sit between the Base Extrusion and boat deck. Take care not to damage the loose Springs that were released to access the mounting holes.
- o. Place a Backup Bar (Item #4) and then a Nylock Nut (Item #2) on the end of each Screw. Tighten with a 9/16" Box End or Open End Wrench. Make sure all hardware is secure.

NOTICE: Use extra care to avoid pinching and damaging the sensor wires that run alongside the Base Extrusion when installing and tightening the mounting hardware.



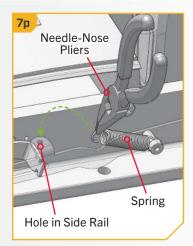
With the mounting hardware secure, reassemble the Springs that were disconnected. Use a Needlenose Pliers to grab the hooked end of the loose Spring. Reconnect it by pulling it upwards and hooking it in the hole on the Side Rail. The curved end of the Spring should be reattached from the top down. Make sure the Spring is not twisted when reattaching it. Reattach the Spring on both the right and left sides of the Base Extrusion.

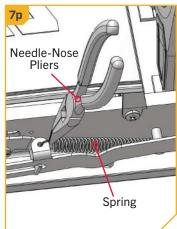
CAUTION

When maneuvering each Spring, carefully handle the Spring to avoid bending it. Do not grab the body of the Spring to avoid pinching between the spring coils. Always grab by the hooked end.

- q. With both Springs reattached, replace the Right Sideplate and Left Sideplate.
- Reinstall the four Sideplate Screws using a #3 Phillips Screwdriver. Two of these screws will be located on each side of the mount. Hand tighten.

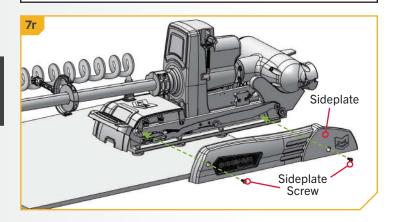
NOTICE: When reinstalling the Sideplates, be sure not to pinch the sensor wires that run alongside the Base Extrusion.





△ CAUTION

When handling each Spring, always keep the spring tension under control. Abruptly releasing the Spring while there is still tension could damage it and cause it to release unpredictably.



BATTERY & WIRING INSTALLATION

BOAT RIGGING & PRODUCT INSTALLATION

For safety and compliance reasons, we recommend that you follow American Boat and Yacht Council (ABYC) standards when rigging your boat. Altering boat wiring should be completed by a qualified marine technician. The following specifications are for general guidelines only:

△ CAUTION

These guidelines apply to general rigging to support your Minn Kota motor. Powering multiple motors or additional electrical devices from the same power circuit may impact the recommended conductor gauge and circuit breaker size. If you are using wire longer than that provided with your unit, follow the conductor gauge and circuit breaker sizing table below. If your wire extension length is more than 25 feet, we recommend that you contact a qualified marine technician.

△ CAUTION

An over-current protection device (circuit breaker or fuse) must be used. Coast Guard requirements dictate that each ungrounded current-carrying conductor must be protected by a manually reset, trip-free circuit breaker or fuse. The type (voltage and current rating) of the fuse or circuit breaker must be sized accordingly to the trolling motor used. The table below gives recommended guidelines for circuit breaker sizing.

CONDUCTOR GAUGE AND CIRCUIT BREAKER SIZING TABLE

This conductor and circuit breaker sizing table is only valid for the following assumptions:

- 1. No more than 2 conductors are bundled together inside of a sheath or conduit outside of engine spaces.
- 2. Each conductor has 105° C temp rated insulation.
- 3. No more than 3% voltage drop allowed at full motor power based on published product power requirements.

Motor Thrust / Max		Circuit Breaker		Wire Extension Length				
Model Amp Draw	Amps	Minimum	5 feet	10 feet	15 feet	20 feet	25 feet	
QUEST 24V	60	60 Amp	24 VDC	6 AWG	6 AWG	4 AWG	4 AWG	2 AWG
QUEST 36V	60	60 Amp	36 VDC	6 AWG	6 AWG	6 AWG	6 AWG	4 AWG

NOTICE: Wire Extension Length refers to the distance from the batteries to the trolling motor leads. Consult website for available thrust options.

Reference

United States Code of Federal Regulations: 33 CFR 183 – Boats and Associated Equipment ABYC E-11: AC and DC Electrical Systems on Boats

SELECTING THE CORRECT BATTERIES

QUEST series motors will operate with any deep cycle marine 12, 24 or 36-volt battery/batteries and have been optimized for use with LiFePO4 lithium-ion battery cells. Lithium-ion batteries maintain higher voltages for more extended periods than lead-acid batteries and will provide the best performance in powering the trolling motor.

QUEST series trolling motors may also be powered with leadacid (flooded, AGM, or GEL) deep-cycle marine 12-volt battery/ batteries. For best results Minn Kota recommends using a deep-cycle marine battery with rating outlined in the "Deep Cycle Amp-Hour Rating" table. Maintain lead-acid batteries at full charge. Proper care will ensure battery power when needed and

Deep Cycle Amp-Hour Rating					
Run Time	Voltage	Group Size	Amp-Hour		
GOOD	12	24	70-85		
BETTER	12	27	85-110		
BEST	12	31	95-125		

significantly improve battery life. Failure to recharge lead-acid batteries (within 12-24 hours) is the leading cause of premature battery failure. Use a multi-stage charger to avoid overcharging. When using Lithium Ion batteries, manufacturers may recommend storing in a semi-charged state and charging fully prior to use.

If using a crank battery to start a gasoline outboard, Minn Kota recommends using a separate battery/batteries for your Minn Kota trolling motor. Always check with the battery manufacturer for specific maintenance, care and storage instructions. Minn Kota also offers a wide selection of chargers to fit your charging needs. For more information on battery selection, rigging, and chargers, please visit minnkota.johnsonoutdoors.com.

⚠ WARNING

Never connect the (+) and the (-) terminals of the same battery together. Take care that no metal object can fall onto the battery and short the terminals. This would immediately lead to a short and extreme fire danger.

△ CAUTION

Refer to "Conductor Gauge and Circuit Breaker Sizing Table" in the previous section to find the appropriate circuit breaker or fuse for your motor. For motors requiring a 60-amp breaker, the Minn Kota MKR-27 60-amp circuit breaker (1865115) is recommended.

△ CAUTION

Please read the following information before connecting your motor to your batteries in order to avoid damaging your motor and/or voiding your warranty.

ADDITIONAL CONSIDERATIONS

Using DC or Alternator Chargers

Your Minn Kota trolling motor may be designed with an internal bonding wire to reduce sonar interference. Most alternator charging systems do not account for this bonding wire, and connect the negative posts of the trolling motor batteries to the negative posts of the crank/starting battery. These external connections can damage connected electronics and the electrical system of your trolling motor, voiding your warranty. Review your charger's manual carefully or consult the manufacturer prior to use to ensure your charger is compatible.

Minn Kota recommends using Minn Kota brand chargers to recharge the batteries connected to your Minn Kota trolling motor, as they have been engineered to work with motors that include a bonding wire. Learn more about Minn Kota chargers online at minnkota.johnsonoutdoors.com.

CONNECTING THE BATTERIES IN SERIES

> Additional Accessories Connected to Trolling Motor Batteries

Significant damage to your Minn Kota motor, your boat electronics, and your boat can occur if incorrect connections are made between your trolling motor batteries and other battery systems. Minn Kota recommends using an exclusive battery system for your trolling motor. Where possible, accessories should be connected to a separate battery system. Radios and sonar units should not be connected to any trolling motor battery systems as interference from the trolling motor is unavoidable. If connecting any additional accessories to any trolling motor battery system, or making connections between the trolling motor batteries and other battery systems on the boat, be sure to carefully observe the information below.

The negative (-) connection must be connected to the negative terminal of the same battery that the trolling motor negative lead connects to. In the diagrams below this battery is labeled "Low Side" Battery. Connecting to any other trolling motor battery will input positive voltage into the "ground" of that accessory, which can cause excess corrosion. Any damage caused by incorrect connections between battery systems will not be covered under warranty.

Automatic Jump Start Systems and Selector Switches

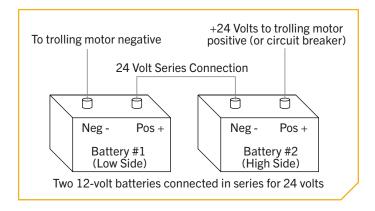
Automatic jump start systems and selector switches tie the negatives of the connected batteries together. Connecting these systems to the "High Side" Battery or "Middle" Battery in the diagrams below and will cause significant damage to your trolling motor and electronics. The only trolling motor battery that is safe to connect to one of these systems is the "Low Side" Battery.

CONNECTING THE BATTERIES IN SERIES (IF REQUIRED FOR YOUR MOTOR)

> 24-Volt Systems

Two 12-volt batteries are required. The batteries must be wired in series, only as directed in the wiring diagram, to provide 24 volts.

- 1. Make sure that the motor is switched off (speed selector on "0").
- 2. Connect a connector cable to the positive (+) terminal of battery 1 and to the negative (-) terminal of battery 2.
- 3. Connect positive (+) red motor lead to positive (+) terminal on battery 2.
- 4. Connect negative () black motor lead to negative () terminal of battery 1.



△ WARNING

For safety reasons do not switch the motor on until the propeller is in the water. If installing a leadwire plug, observe proper polarity and follow instructions in your boat owner's manual.

▲ WARNING

• For safety reasons, disconnect the motor from the battery or batteries when the motor is not in use or while the battery/batteries are being charged.

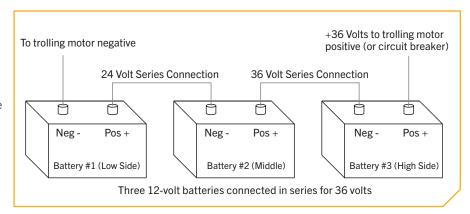
- Improper wiring of 24/36 volt systems could cause battery explosion.
- Keep leadwire wing nut connections tight and solid to battery terminals.
- Locate battery in a ventilated compartment.

CONNECTING THE BATTERIES IN SERIES

36-Volt Systems

Three 12-volt batteries are required. The batteries must be wired in series, only as directed in the wiring diagram, to provide 36 volts.

- 1. Make sure that the motor is switched off (speed selector on "0").
- 2. Connect a connector cable to the positive (+) terminal of battery 1 and to the negative (–) terminal of battery 2 and another connector cable from the positive (+) terminal of battery 2 to the negative (–) terminal of battery of battery 3.
- 3. Connect positive (+) red motor lead to positive (+) terminal on battery 3.
- 4. Connect negative () black motor lead to negative (-) terminal of battery 1.



⚠ WARNING

For safety reasons, do not switch the motor on until the propeller is in the water. If installing a leadwire plug, observe proper polarity and follow instructions in your boat owner's manual.

△ WARNING

For safety reasons, disconnect the motor from the battery or batteries when the motor is not in use or while the battery/batteries are being charged.

- Improper wiring of 24/36 volt systems could cause battery explosion.
- Keep leadwire wing nut connections tight and solid to battery terminals.
- Locate battery in a ventilated compartment.

COMPLETING THE INSTALLATION

COMPLETING THE TERROVA QUEST INSTALLATION

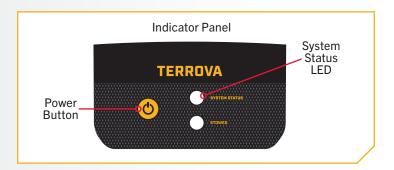
The Terrova QUEST is an advanced trolling motor. To maximize its performance, mechanical and electrical systems should be set and calibrated to fit every user's installation. This portion of the installation will cover how to verify power, install the Bow-mount Stabilizer, and more. The installation will conclude with connecting Accessory Cables and setting motor preferences for ease of use. Minn Kota recommends connecting the trolling motor to the One-Boat Network app to assist in these steps. Find more information in the One-Boat Network App document included with the trolling motor or the One-Boat Network Owner's Manual found online at minnkota.johnsonoutdoors.com.

COMPLETING THE INSTALLATION >

Verifying Power

Each time the trolling motor is powered "on," the control board will auto-detect the power supplied from the battery system and adjust the thrust output based on a 24V or 36V battery system. To verify power to the trolling motor, connect the Terrova QUEST to power. At specific points in the installation, power will be disconnected or turned "off" to ensure a safe environment for installation.

- 1
- a. Locate the Indicator Panel at the front of the Mount.
 Power on the trolling motor by pressing the Power
 button on the Indicator Panel. When the trolling motor is on, the System Status
- b. To turn the motor "off," press and release the Power button. When the Motor is powered off, the System Status LED will not be illuminated.



NOTICE: In instances where the trolling motor is updating, the System Status LED will flash blue while the update is performed. Once the update is complete, the system will self-reboot and perform the normal start-up sequence. If a standard power-up sequence is not experienced, refer to the "Troubleshooting" section of this manual to identify any errors. To learn more about software updates, see the Owner's Manual for the Advanced GPS Navigation Wireless Remote online at minnkota.johnsonoutdoors.com.

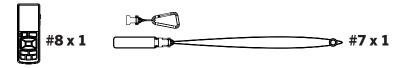
Installing the Bow-Mount Stabilizer

Terrova QUEST motors with a 72" shaft length come with an MKA-60 Bow-Mount Stabilizer Kit (Item #9 and Assembly #E). This accessory stabilizes the shaft and control head when the motor is stowed for transport. Motors with shaft lengths under 72" may purchase the MKA-60 separately as an optional accessory (1862060). For instructions on installing the MKA-60 to the Terrova QUEST, refer to the document provided with the Bow-Mount Stabilizer Kit.

POWERING ON THE WIRELESS REMOTE

Powering on the Wireless Remote

ITEM(S) NEEDED



- Power on the trolling motor.
- b. To turn on the Wireless Remote (Item #8), press and hold the Power button on the side of the Remote.
- c. A message will appear on the display screen. Read the disclaimer, then press the Steer Right button to select "I Agree."
- d. The content on the display screen will populate. Remote functions to manually control the motor are now active, including Speed Up , Speed Down , Steer Left 3, Steer Right 5, and Prop On/Off.
- e. When the Advanced GPS Navigation system has obtained a minimum GPS signal strength of one bar, all remaining functions will become available.

NOTICE: Attaching the Lanyard (Item #7) to the Wireless Remote is optional.





NOTICE: The Wireless Remote comes from the factory paired to the Terrova QUEST.

NOTICE: A Remote Cradle accessory (1866675) can be purchased for mounting the Wireless Remote or attaching the Remote to a belt clip.

INSTALLING THE FOOT PEDAL

Installing the Foot Pedal

1

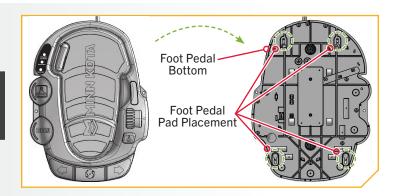
ITEM(S) NEEDED

____ #14 x 4



Take the Foot Pedal (Item #C) and turn it over.
 Put a Foot Pedal Pad (Item #14) in each of the pad locations.

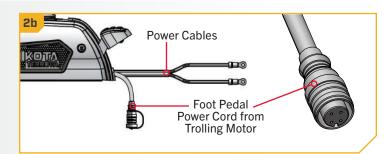
NOTICE: Adding the Foot Pedal pads is optional. The pads are recommended when using the Foot Pedal on non-carpeted surfaces.

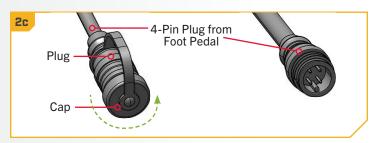


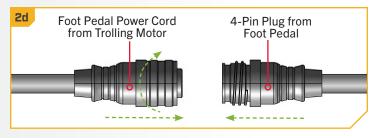
- 2
- Locate the Foot Pedal Power Cord that exits the Mount of the trolling motor, next to the Power Cables. Unscrew the Cap on the Plug at the end of the Foot Pedal Power Cord.
- c. Locate the 4-Pin Plug from the Foot Pedal and unscrew the Cap.
- d. Align the 4-Pin Plug from the Foot Pedal with the Plug from the trolling motor. Firmly push the Plugs together. Secure the connection by rotating the collar on the Foot Pedal Power Cord in a clockwise direction.

NOTICE: The connectors are keyed to prevent reversed installation.

NOTICE: When the Foot Pedal Power Cord is not in use, ensure that the Cap is on and firmly secured.





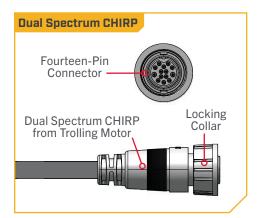


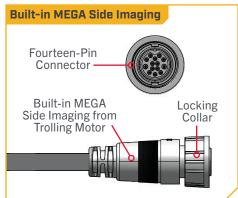
IDENTIFYING TROLLING MOTOR FEATURES AND THEIR ASSOCIATED CABLES

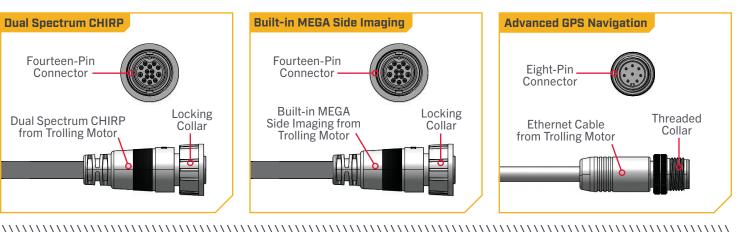
IDENTIFYING TROLLING MOTOR FEATURES AND THEIR ASSOCIATED CABLES

Feature & Cable Identification

The Terrova QUEST is pre-installed with Advanced GPS Navigation - including the ability to connect via Ethernet to a Humminbird unit. The motor is also pre-installed with sonar, either Dual Spectrum CHIRP or Built-in MEGA Side Imaging. These features may be installed on their own or in combination with another feature. All of these features require Accessory Cables to be connected to an output device. The connectors are present on the trolling motor and have cables that exit below the Control Head. To better identify Accessory Cables present, refer to the diagrams that detail what the Dual Spectrum CHIRP, Built-in MEGA Side Imaging and Advanced GPS Navigation connectors look like.





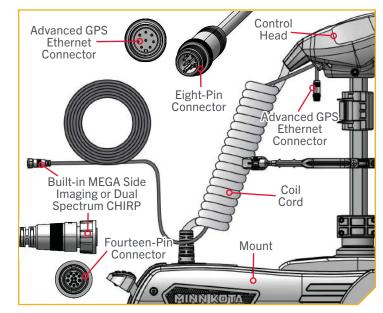


Identifying Connectors

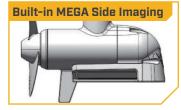
Two connectors are present below the Control Head. The trolling motor will be equipped with:

Advanced GPS Navigation & Dual Spectrum CHIRP or Built-in MEGA Side Imaging - Advanced GPS Navigation is pre-installed on your trolling motor. One Eight-Pin Advanced GPS Ethernet Connector will exit the base of the Control Head and rest just below the Control Head next to the Coil Cord. If the Advanced GPS Navigation on the trolling motor will be used with a fish finder, an Ethernet Cable may be attached to the Advanced GPS Ethernet Connector below the Control Head. See the "Advanced GPS Navigation" section of this document for details on how to install the Advanced GPS Ethernet Connector to a Humminbird.

Dual Spectrum CHIRP or Built-in MEGA Side Imaging is also pre-installed on your trolling motor. One Sonar Accessory Cable will exit the base of the Control Head and run down the center of the Coil Cord. The end of this Cable has a Fourteen-Pin Connector. Motors with Dual Spectrum CHIRP or Built-in MEGA Side Imaging will also have a transducer in the Lower Unit. The appearance of the transducer will vary depending on sonar type.







FEATURE & CABLE MANAGEMENT

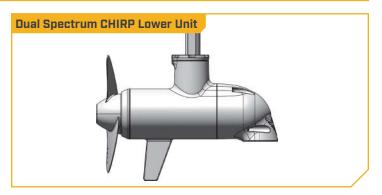
> Feature & Cable Management

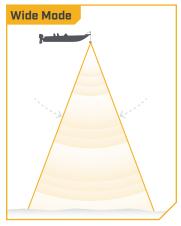
DUAL SPECTRUM CHIRP >

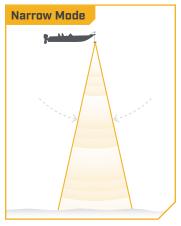
Your trolling motor may be pre-installed with a transducer system featuring Humminbird's Dual Spectrum CHIRP. CHIRP stands for "Compressed High Intensity Radar Pulse." Dual Spectrum CHIRP is a 2D sonar transducer with a temperature sensor that is integrated into the lower unit of the trolling motor. Humminbird also utilizes a proprietary, best-in-class transducer designed and built to maximize fish detail, as well as coverage area. Dual Spectrum CHIRP scans the water for fish similar to the way the seek function on your truck's radio scans the airwaves for FM stations. By covering a wide range of frequencies, CHIRP produces more accurate, more detailed returns of fish, structure, and the bottom.

Humminbird's Dual Spectrum CHIRP gives you full spectrum capability, plus the power to select your own start and end frequencies by operating in two different modes. Wide Mode for maximum coverage and Narrow Mode for maximum detail. Wide mode allows you to search deep and wide. Is it used for watching your lure while vertical jigging, or gaining a more expansive view in shallow water. Narrow Mode is used to hone in on the small stuff that makes a big difference. Narrow Mode provides a precise perspective of the water below, helping you target individual fish, or identify fish hidden in structure and/or tight to the bottom.

Dual Spectrum CHIRP features:



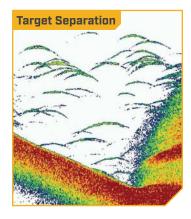


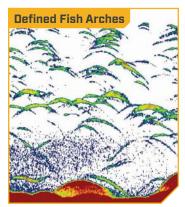


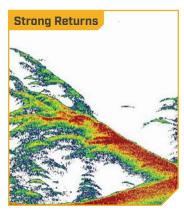
SUPERIOR TARGET SEPARATION - Separating fish from their habitat is the name of the game. And now, you'll be able to tell the difference more easily between bait and game fish, and nearby structure and vegetation.

CLEARLY DEFINED FISH ARCHES - We've got bad news for your arch nemesis. Large game fish will show up on your screen as long, well-defined arches, for quick identification and accurate lure presentation.

STRONG RETURNS WITHOUT NOISE - Stop seeing things that aren't there. A high signal-to-noise ratio translates to better defined targets, less clutter and greater certainty that what you're looking at on-screen is legit.







The integrated design of the Dual Spectrum CHIRP transducer protects it in the lower unit of the trolling motor from underwater hazards and prevents tangles and damage to the transducer cables. In certain situations, air bubbles may adhere to the surface of the Dual Spectrum CHIRP transducer and affect the performance. If this happens, simply wipe the surface of the transducer with your finger.

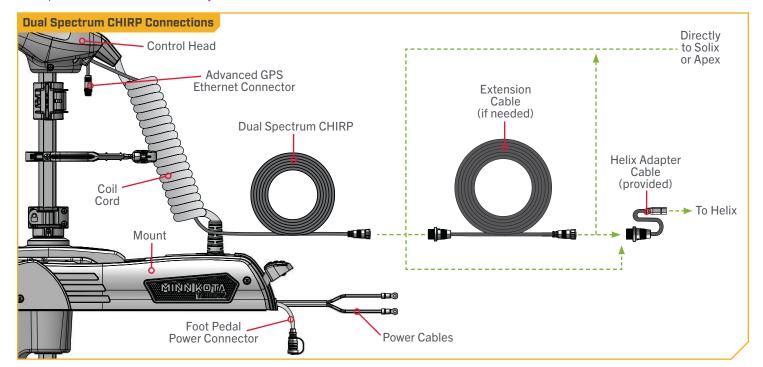
Considerations for Connecting and Routing Dual Spectrum CHIRP

If Dual Spectrum CHIRP is pre-installed on your trolling motor, one Dual Spectrum CHIRP accessory cable will exit the base of the Control Head and run down the center of the Coil Cord. Dual Spectrum CHIRP requires cables to be connected to an output device such as a Humminbird® fish finder. The Dual Spectrum CHIRP cable that exits the Control Head is "Apex and Solix Ready." Connecting the trolling motor equipped with a Dual Spectrum CHIRP transducer to a compatible fish finder gives you a 2D sonar view of what is happening directly below your trolling motor. To determine if your fish finder is compatible with Dual Spectrum CHIRP, please visit minnkota.johnsonoutdoors.com to check compatibility. The Dual Spectrum CHIRP cable from the trolling motor may be plugged directly into a Solix or Apex, directly into an Extension Cable or directly into a Humminbird® Helix Adapter Cable.

EXTENSION CABLES - The Dual Spectrum CHIRP cable from the trolling motor may not be long enough to reach your fish finder. If the cable length does not reach the desired fish finder installation location, extension cables are available. A 10-foot extension cable (EC M3 14W10 - 10' transducer extension cable - 720106-1) and a 30-foot extension cable (EC M3 14W30 - 30' transducer extension cable - 720106-2) are available from humminbird, johnsonoutdoors.com. Both the 10-foot and 30-foot extension cables also come "Apex and Solix Ready." The Extension Cables may plug directly into a Solix or Apex or directly into a Helix Adapter Cable.

HUMMINBIRD HELIX ADAPTER CABLES - If connecting to a Humminbird® Helix fish finder, an adapter cable accessory is included that will allow the connection of any compatible Humminbird® Helix fish finder. The Helix adapter cable will plug directly into the Helix fish finder.

OTHER FISH FINDER ADAPTER CABLES - If connecting to other fish finders on the market, check for compatibility or any required adapter cables online at minnkota.johnsonoutdoors.com.



DUAL SPECTRUM CHIRP

All Dual Spectrum CHIRP Terrova QUEST motors are equipped with an internal bonding wire. Incorrect rigging will cause sonar interference and can damage your trolling motor, electronics, and other boat accessories. To minimize trolling motor interference, ensure that the fish finder and trolling motor are powered by separate batteries. Please refer to the "Battery & Wiring Installation" and "Motor Wiring Diagram" sections of this manual for correct rigging instructions.

The Dual Spectrum CHIRP cables are shielded to minimize interference. To protect this shielding, the cables should not be pulled tight against sharp angles or hard objects. If using cable ties, do not over-tighten. Any excess cable should be bundled in a loose loop of no less than 4" in diameter. The connection cable should be routed to the fish finder following Minn Kota recommendations on routing the cables to optimize mobility and maximize functionality. Follow the instructions below for completing all connections and then follow the instructions for "Securing Accessory Cables" to complete the output cable installation.

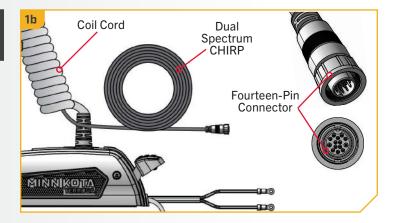
△ CAUTION

Failure to follow the recommended wire routing for installed features, if equipped, may cause damage to the product and void your product warranty. Route cables away from pinch points or other areas that may cause them to bend in sharp angles. Routing the cables in any way other than directed may cause damage to the cables by being pinched or severed. Do not over-tighten the cable ties as it may damage the wires.

1

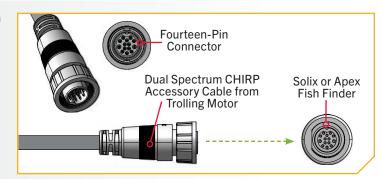
NOTICE: Your fish finder should be turned off until this procedure is complete.

- a. Place the motor in the deployed position.
- b. Locate the Fourteen-Pin Connector at the end
 of the Dual Spectrum CHIRP accessory cable.
 The cable will exit the base of the Control Head and
 run down the center of the Coil Cord.
- Determine if the Plug on the end of the Dual Spectrum CHIRP accessory cable will be attached directly to:
 - 1) a Humminbird® Solix or Apex fish finder,
 - 2) a Dual Spectrum CHIRP Extension Cable,
 - 3) a Helix Adapter Cable or a compatible fish finder adapter cable.

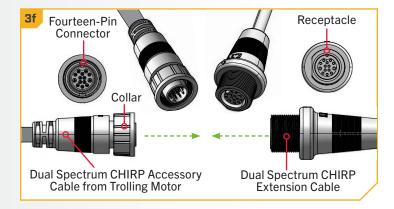


DUAL SPECTRUM CHIRP

- If installing directly to a Solix or Apex, the connection will be flat on the back of the fish finder display.
- e. Align the pins on the Accessory Cable with the receptacle on the fish finder. Notice the keyed connectors. Tighten the Collar from the accessory cable to secure the connection. Once directly installed to the Solix or Apex, the connection is complete.



- If installing directly to a Dual Spectrum CHIRP Extension Cable, align the pins on the accessory cable with the receptacle on the extension cable. Notice the keyed connectors. Tighten the Collar from the accessory cable to secure the connection.
- g. If the Dual Spectrum CHIRP extension cable will be attached directly to a Humminbird® Solix or Apex, the connection will look exactly like the installation directly into a Humminbird Solix or Apex fish finder.



NOTICE: A 10-foot extension cable (EC M3 14W10 - 10' transducer extension cable - 720106-1) and a 30-foot extension cable (EC M3 14W30 - 30' transducer extension cable - 720106-2) are available from humminbird.johnsonoutdoors.com.

DUAL SPECTRUM CHIRP

4

ITEM(S) NEEDED

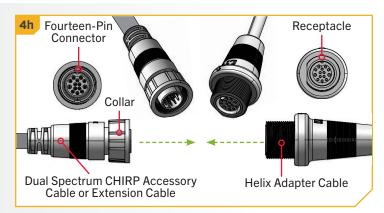


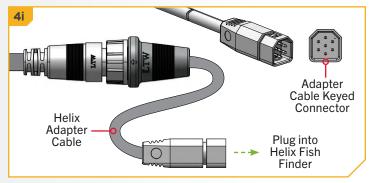
- h. If installing directly to a Helix Adapter Cable, align the pins on the accessory cable or extension cable with the receptacle on the Helix Adapter Cable (Item #18). Notice the keyed connectors. Tighten the Collar from the accessory cable or extension cable to secure the connection.
- If the Helix Adapter Cable will be attached directly to a Humminbird® Helix, plug it in the Helix Adapter Cable Keyed Connection on the back of the fish finder.

NOTICE: If connecting to other fish finders on the market, check for compatibility or any required adapter cables online at minnkota.johnsonoutdoors.com.

j. If the trolling motor has more than one external connector for an output device, complete the connection for that specific output and then follow the instructions for "Securing Accessory Cables" to complete the output cable installation.

NOTICE: If unsure of what features the trolling motor may be installed with that require connection to an output device, please review the "Identifying Trolling Motor Features and Their Associated Cables" section in this document.





BUILT-IN MEGA SIDE IMAGING >

MEGA Imaging technology took fish finding into the megahertz frequency for the very first time. Now Built-in MEGA Side Imaging+ delivers up to 3X the output of standard Side Imaging®. Humminbird improved this technology even further by extending the depth range and expanding the side coverage areas, all while improving the crystal clear imagery. Built-in MEGA Side Imaging+ comes available in the Minn Kota flagship families of trolling motors, including Ultrex and Ulterra, with 200 feet of coverage on either side of your boat. With Humminbird MEGA imaging sonar built right into the trolling motor, you now have a crystal clear view of what's directly to the left and right of your boat, without having to manage all of the cables that come with external transducers. The Built-in MEGA SI transducer is only available on new models equipped from the factory and cannot be added to an existing trolling motor.

Considerations for Connecting and Routing Built-in MEGA Side Imaging

If Built-in MEGA Side Imaging is pre-installed on your trolling motor, one Built-in MEGA Side Imaging accessory cable will exit the base of the Control Head and run down the center of the Coil Cord. Built-in MEGA Side Imaging requires cables to be connected to an output device such as a Humminbird® fish finder. The Built-in MEGA Side Imaging cable that exits the Control Head is "Apex and Solix Ready." Connecting the trolling motor equipped with a Built-in MEGA Side Imaging transducer to a compatible fish finder gives you a 2D sonar view of what is happening directly below your trolling motor. To determine if your fish finder is compatible with Built-in MEGA Side Imaging, please visit minnkota.johnsonoutdoors.com to check compatibility. The Built-in MEGA Side Imaging cable from the trolling motor may be plugged directly into a Solix or Apex, directly into an Extension Cable or directly into a Humminbird® Helix Adapter Cable.

EXTENSION CABLES - The Built-in MEGA Side Imaging cable from the trolling motor may not be long enough to reach your fish finder. If the cable length does not reach the desired fish finder installation location, extension cables are available. A 10-foot extension cable (EC M3 14W10 - 10' transducer extension cable - 720106-1) and a 30-foot extension cable (EC M3 14W30 - 30' transducer extension cable - 720106-2) are available from humminbird.johnsonoutdoors.com. Both the 10-foot and 30-foot extension cables also come "Apex and Solix Ready." The Extension Cables may plug directly into a Solix or Apex or directly into a Helix Adapter Cable.

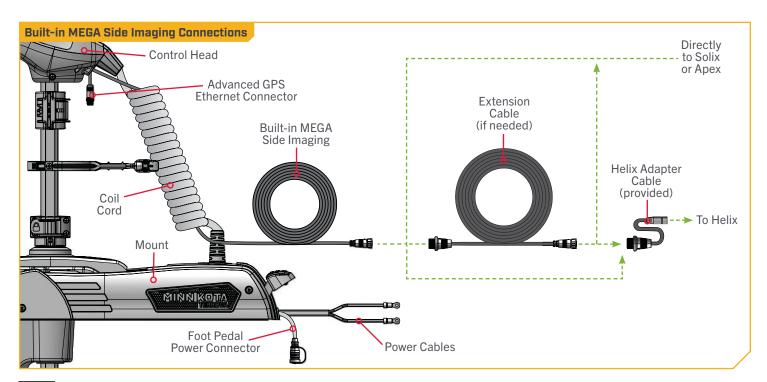
HUMMINBIRD HELIX ADAPTER CABLES - If connecting to a Humminbird® Helix fish finder, an adapter cable accessory is included that will allow the connection of any compatible Humminbird® Helix fish finder. The Helix adapter cable will plug directly into the Helix fish finder.

OTHER FISH FINDER ADAPTER CABLES - If connecting to other fish finders on the market, check for compatibility or any required adapter cables online at minnkota.johnsonoutdoors.com.

△ CAUTION

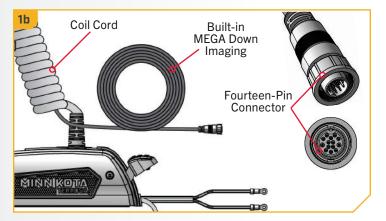
Failure to follow the recommended wire routing for installed features, if equipped, may cause damage to the product and void your product warranty. Route cables away from pinch points or other areas that may cause them to bend in sharp angles. Routing the cables in any way other than directed may cause damage to the cables by being pinched or severed. Do not over-tighten the cable ties as it may damage the wires.

NOTICE: You can only view Side Imaging with a MEGA DI or MEGA SI HELIX G2N, G3N or G4N Series model and a required adapter, or with any SOLIX or APEX Series model. The built-in transducer cannot supply MEGA Imaging to Humminbird models that do not already have the capability. If you have a G2/G2N, G3/G3N, G4/G4N HELIX that is not a MEGA SI or MEGA DI model, you will still get 2D Dual Spectrum CHIRP Sonar from the transducer. SOLIX G1 and HELIX G2 and G2N units need to be running the latest software update to view sonar from motors with Built-in MEGA Imaging. You can get the latest version of software for your fish finder on humminbird.johnsonoutdoors.com. Built-in MEGA Imaging is not supported by HELIX G1 models or other brands of fish finders.

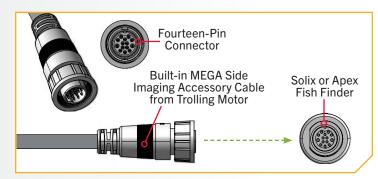


NOTICE: Your fish finder should be turned off until this procedure is complete.

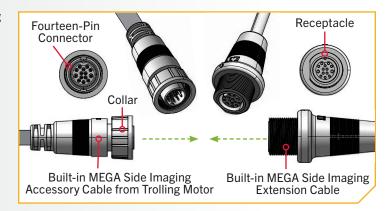
- Place the motor in the deployed position.
- b. Locate the Fourteen-Pin Connector at the end of the Built-in MEGA Side Imaging accessory cable. The cable will exit the base of the Control Head and run down the center of the Coil Cord.
- c. Determine if the Plug on the end of the Builtin MEGA Side Imaging accessory cable will be attached directly to:
 - 1) a Humminbird® Solix or Apex fish finder,
 - 2) a Built-in MEGA Side Imaging Extension Cable,
 - 3) a Helix Adapter Cable or a compatible fish finder adapter cable.



- If installing directly to a Solix or Apex, the connection will be flat on the back of the fish finder display.
- e. Align the pins on the Accessory Cable with the receptacle on the fish finder. Notice the keyed connections. Tighten the Collar from the accessory cable to secure the connection. Once directly installed to the Solix or Apex, the connection is complete.



- If installing directly to a Built-in MEGA Side Imaging Extension Cable, align the pins on the accessory cable with the receptacle on the extension cable. Notice the keyed connectors. Tighten the Collar from the accessory cable to secure the connection.
- g. If the Built-in MEGA Side Imaging Extension Cable will be attached directly to a Humminbird® Solix or Apex, the connection will look exactly like the installation directly into a Humminbird Solix or Apex fish finder.



NOTICE: A 10-foot extension cable (EC M3 14W10 - 10' transducer extension cable - 720106-1) and a 30-foot extension cable (EC M3 14W30 - 30' transducer extension cable - 720106-2) are available from humminbird.johnsonoutdoors.com.

ITEM(S) NEEDED

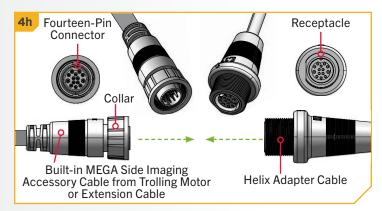


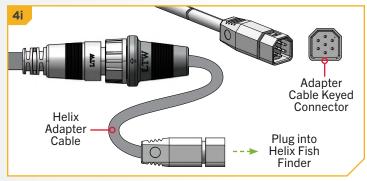
- h. If installing directly to a Helix Adapter Cable, align the pins on the accessory cable or extension cable with the receptacle on the Helix Adapter Cable (Item #18). Notice the keyed connectors. Tighten the Collar from the accessory cable or extension cable to secure the connection.
- If the Helix Adapter Cable will be attached directly to a Humminbird® Helix, plug it in the Helix Adapter Cable Keyed Connection on the back of the fish finder.

NOTICE: If connecting to other fish finders on the market, check for compatibility or any required adapter cables online at minnkota.johnsonoutdoors.com.

If the trolling motor has more than one external connector for an output device, complete the connection for that specific output and then follow the instructions for "Securing Accessory Cables" to complete the output cable installation.

NOTICE: If unsure of what features the trolling motor may be installed with that require connection to an output device, please review the "Identifying Trolling Motor Features and Their Associated Cables" section in this document.





ADVANCED GPS NAVIGATION

ADVANCED GPS NAVIGATION >

Your Minn Kota trolling motor and Humminbird fish finder communicate with each other to change the way you fish. Advanced GPS Navigation offers a large array of features including controlling speed, steering, Spot-Lock, and the ability to record and retrace paths on the water, all at your fingertips. To learn more about the GPS capabilities available with your new motor, please refer to the Advanced GPS Navigation Owner's Manual by visiting minnkota.johnsonoutdoors.com.

The Wireless Remote and GPS controller make up the Advanced GPS Navigation system. A Wireless Remote comes paired to the controller from the factory. The GPS controller contains a very sensitive compass and is where all GPS satellite and remote signals are received. The GPS controller is located in the trolling motor Control Head and may be connected to a fish finder from a connection cable that exits the Control Head. If the Advanced GPS Navigation system will be used with a fish finder, the Ethernet link between the trolling motor and the fish finder should be connected.

Considerations for Connecting and Routing Advanced GPS Navigation

Advanced GPS Navigation is pre-installed on your trolling motor. One eight-pin Advanced GPS Ethernet Connector will exit the base of the Control Head and rest just below the Control Head next to the Coil Cord. If the Advanced GPS Navigation on the trolling motor will be used with a fish finder, an Ethernet Cable will need to be attached to the Advanced GPS Ethernet Connector below the Control Head. Consider the distance between the trolling motor and the fish finder to determine how to complete the Ethernet connection.

ETHERNET CABLES - Minn Kota provides one 30 ft Ethernet cable (AS EC 30E - 30' Ethernet Cable - 720073-4) with every trolling motor equipped with Advanced GPS Navigation. The 30 ft Ethernet cable will accommodate a standard Ethernet connection for most installations to a Humminbird fish finder and is "Apex and Solix Ready." If the distance between the trolling motor and Humminbird fish finder is relatively small and a shorter cable is preferred, alternate cable lengths are available from humminbird.johnsonoutdoors.com. These options include:

- 10 ft (AS EC 10E 10' Ethernet Cable 720073-2)
- 15 ft (AS EC 15E 15' Ethernet Cable 720073-5)
- 20 ft (AS EC 20E 20' Ethernet Cable 720073-3)

Every length of Ethernet cable plugs directly into a Solix or Apex or directly into a Helix Adapter Cable.

HUMMINBIRD HELIX ADAPTER CABLES - Minn Kota provides one Helix Adapter Cable (AS EC QDE - Ethernet Adapter Cable -720074-1) with every trolling motor equipped with Advanced GPS Navigation. If the Ethernet connection is being made between the trolling motor and any Humminbird® Helix fish finder, the Helix Adapter Cable should be used. The Helix Adapter Cable directly connects the Ethernet Cable to a Helix fish finder.

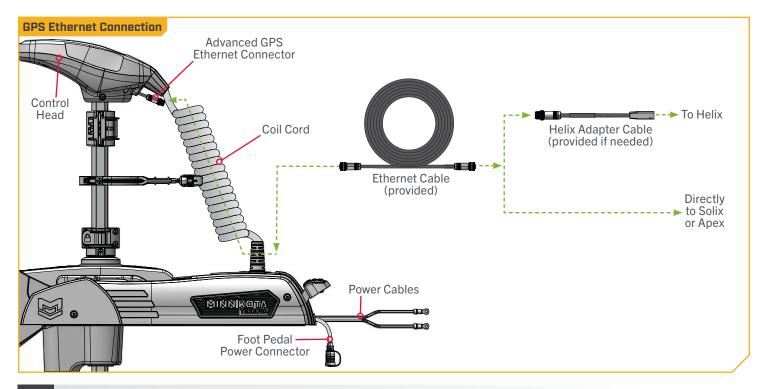
ETHERNET EXTENSION CABLES - If the 30 ft Ethernet cable provided with your trolling motor with Advanced GPS Navigation is not long enough to reach the fish finder, an Ethernet Extension cable should be used. The Ethernet Extension cable is available from humminbird.johnsonoutdoors.com and is available in a 30 ft length (AS ECX 30E - 30' Ethernet Extension Cable - 760025-1). The Ethernet Extension Cable will plug directly into any length of Ethernet cable.

NOTICE: Minn Kota recommends routing the Ethernet Cable or Ethernet Extension Cable through the Coil Cord when making the Ethernet connection. The cables will be installed from the Mount to the Control Head through the Coil Cord and parallel to the Dual Spectrum CHIRP or Built-in MEGA Side Imaging Cable. Bypassing the Coil Cord when routing the Ethernet Cable or Ethernet Extension Cable is not recommended.

△ CAUTION

Failure to follow the recommended wire routing for installed features, if equipped, may cause damage to the product and void your product warranty. Route cables away from pinch points or other areas that may cause them to bend in sharp angles. Routing the cables in any way other than directed may cause damage to the cables by being pinched or severed. Do not over-tighten cable ties as it may damage the wires.

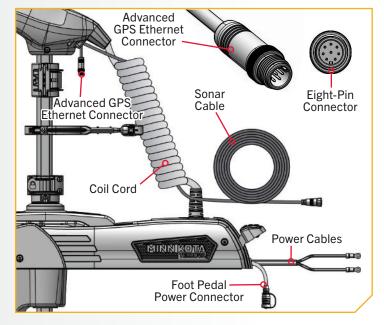
ADVANCED GPS NAVIGATION



NOTICE: Your fish finder should be turned off until this procedure is complete.

- Place the motor in the deployed position.
- b. Locate the Eight-Pin Advanced GPS Ethernet Connector below the Control Head. The Advanced GPS Ethernet Connector will exit the base of the Control Head and will rest just below the Control Head next to the Coil Cord.

NOTICE: Terrova QUEST trolling motors with Advanced GPS Navigation are also equipped with Sonar. Sonar is pre-installed from the factory and may be either Dual Spectrum CHIRP or Built-in MEGA Side Imaging. A Sonar Cable will run down the center of the Coil Cord. Review the "Identifying Trolling Motor Features and Their Associated Cables" section of this document to identify and learn more about Sonar.



ITEM(S) NEEDED

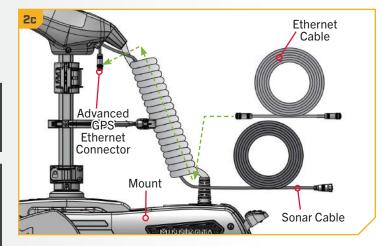


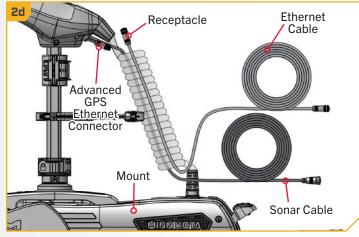
Identify the keyed Receptacle on the Ethernet Cable (Item #15). It will be keyed to fit with the Eight-Pin Advanced GPS Ethernet Connector below the Control Head.

NOTICE: The Ethernet Cable has a Receptacle for the Advanced GPS Ethernet Connector on both ends. Either end may be connected.

NOTICE: The 30' Ethernet Cable (AS EC 30E - 30' Ethernet Cable - 720073-4) is provided. If a different length is preferred, alternate cable lengths are available from humminbird.johnsonoutdoors.com.

d. Take the Receptacle on the Ethernet Cable and run it through the center of the Coil Cord, starting at the end of the Coil Cord attached to the Mount and working up towards the Control Head. The Ethernet Cable should be parallel to the Sonar Cable. Allow enough slack in the cable to attach the Receptacle to the Advanced GPS Ethernet Connector.





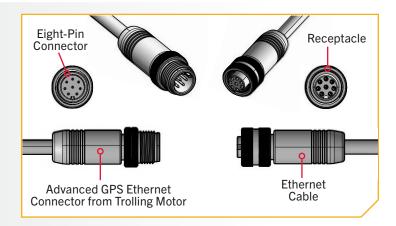
ADVANCED GPS NAVIGATION

3

e. To install the Ethernet Cable, align the pins on the Advanced GPS Ethernet Connector with the Receptacle on the Ethernet Cable. Notice the keyed connectors. Tighten the Collar from the Ethernet Cable to secure the connection.

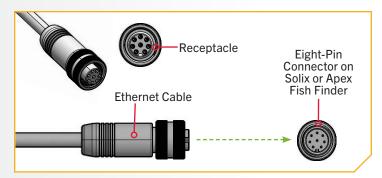
- f. The Ethernet Cable will plug directly into a Solix or Helix Fish Finder or directly into a Helix Adapter Cable.
- g. If the trolling motor has more than one feature that requires connection to an output device, complete the connection for that specific output and then follow the instructions for "Securing Accessory Cables" to complete the Accessory Cable installation.

NOTICE: Once all accessory cables are connected, the final installation will require any cables present to be secured together. The final installation will vary based on motor features. See the "Securing Accessory Cables" section of this document for details once all connections are complete.



NOTICE: A 30' Ethernet Extension Cable (AS ECX 30E - 30' Ethernet Extension Cable - 760025-1) is available from humminbird.johnsonoutdoors.com and should be used if the standard 30' Ethernet Cable provided with the trolling motor is not long enough to reach the fish finder.

- h. If installing directly to a Solix or Apex, the connector will be flat on the back of the fish finder display.
- i. Align the Receptacle on the Ethernet Cable with the Eight-Pin Connector on the Apex or Solix fish finder. Notice the keyed connectors. Tighten the Collar from the Ethernet Cable to secure the connection. Once directly installed to the Solix or Apex, the connection is complete.



ADVANCED GPS NAVIGATION

5

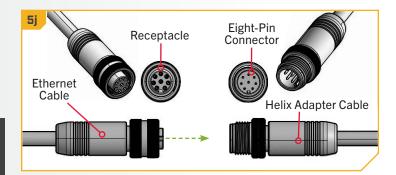
ITEM(S) NEEDED

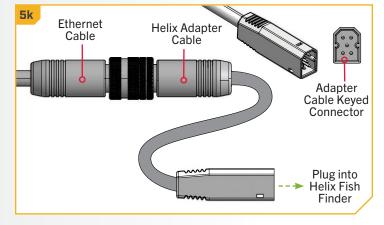


j. If installing directly to a Helix Adapter Cable (Item #16), align the Receptacle on the Ethernet Cable with the Eight-Pin Connector on the Helix Adapter Cable provided. Notice the keyed connectors. Tighten the Collar from the Ethernet Cable to secure the connection.

NOTICE: Minn Kota provides one Helix Adapter Cable (AS EC QDE - Ethernet Adapter Cable - 720074-1) with every trolling motor equipped with Advanced GPS Navigation.

k. The Helix Adapter Cable directly connects the Ethernet Cable to a Helix fish finder. Locate the Helix Adapter Cable Keyed Connector on the back of the fish finder. Plug the Helix Adapter Cable into the back of the Helix fish finder to complete the connection.





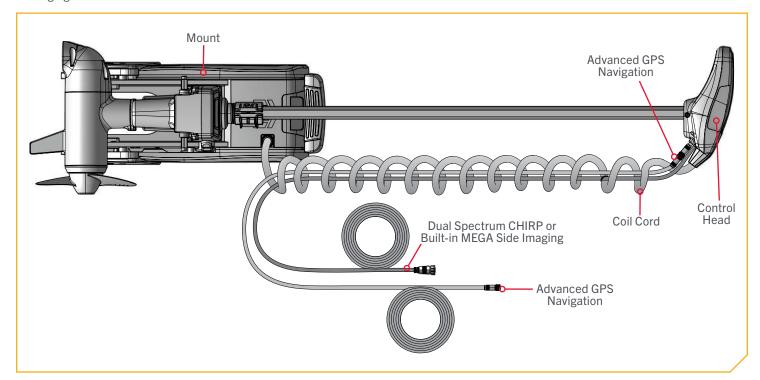
SECURING ACCESSORY CABLES

Securing Accessory Cables

Before securing accessory cables, please review the "Identifying Trolling Motor Features and Their Associated Cables" section of this

NOTICE: If **only one** cable is present below the Control Head, this installation is not applicable.

document. When identifying features, it is very important to secure the cables if **two** connections are present below the Control Head. If only **one** cable is present below the Control Head, securing the Accessory Cables is not necessary. All Accessory Cables that will be used on the trolling motor must be routed and all connections secured before completing the installation in this section. To review how feature cables should be routed and connected, review the "Advanced GPS Navigation" and "Dual Spectrum CHIRP" or "Built-in MEGA Side Imaging" sections of this document.



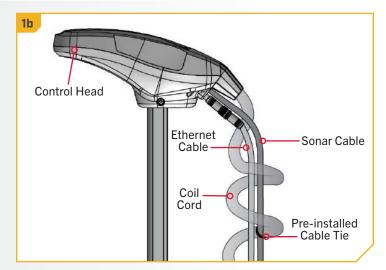
△ CAUTION

Failure to follow the recommended wire routing for installed features, if equipped, may cause damage to the product and void your product warranty. Route cables away from pinch points or other areas that may cause them to bend in sharp angles. Routing the cables in any way other than directed may cause damage to the cables by being pinched or severed. Do not over-tighten the cable ties as it may damage the wires.

SECURING ACCESSORY CABLES

- Place the motor in the stowed position. Confirm all Accessory Cables are connected to an output device as desired.
- b. To secure the Accessory Cables, the Sonar Cable and Ethernet Cable will be tied together inside the Coil Cord using Cable Ties. Ensure the Accessory Cables are parallel to each other inside the Coil Cord. Run the Accessory Cables from the Control Head to the Mount, keeping them straight and parallel the entire length.

NOTICE: The Sonar Cable comes from the factory secured to the Coil Cord with a pre-installed Cable Tie. Keep the pre-installed Cable Tie in place.



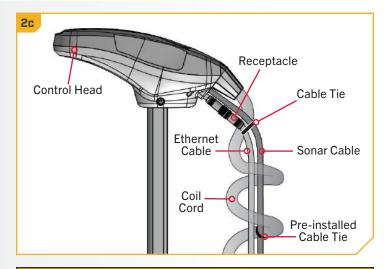
ITEM(S) NEEDED

#17 x 10

- c. Starting below the Control Head, take a Cable Tie (Item #17) and place it directly below the Receptacle on the Ethernet Cable. The Cable Tie should be just below the Receptacle. Keep the pre-installed Cable Tie in place.
- d. Wrap the Cable Tie around the Sonar Cable and Ethernet Cable. Do NOT capture the Coil Cord with the Cable Tie. The Sonar Cable and Ethernet Cable should be secured together with the Cable Tie but float freely inside the Coil Cord.

NOTICE: Do NOT secure the Accessory Cables to the Coil Cord. ONLY secure the Sonar and Ethernet Cables to each other using Cable Ties.

e. Secure the Cable Tie around the Accessory Cables until it is fingertip tight. Do not over-tighten the Cable Tie as it may damage the Cables.



△ CAUTION

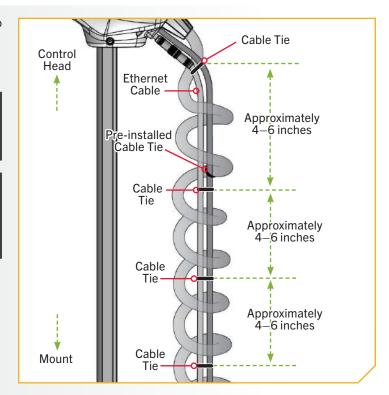
Do not over-tighten the Cable Ties as they may damage the wires.

SECURING ACCESSORY CABLES

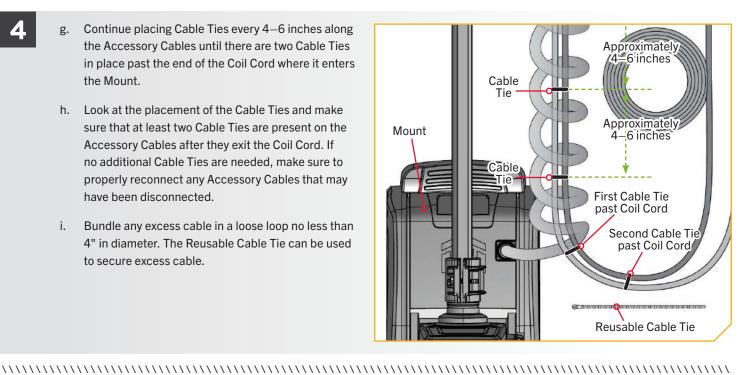
Follow the Accessory Cables from the Control Head to the Mount and place additional Cable Ties every 4-6 inches. The number of Cable Ties needed will vary depending on the length of the trolling motor Shaft.

NOTICE: If additional Cable Ties are needed, a Cable Tie Bag Assembly (Part #2996300) is available from the Parts Ordering Portal at minnkota.johnsonoutdoors.com.

NOTICE: Secure the Cable Ties fingertip tight. It is recommended to have them **ONLY** tight enough so that they do not slide around on the Accessory Cables and hold the Cables together.



- Continue placing Cable Ties every 4-6 inches along the Accessory Cables until there are two Cable Ties in place past the end of the Coil Cord where it enters the Mount.
- h. Look at the placement of the Cable Ties and make sure that at least two Cable Ties are present on the Accessory Cables after they exit the Coil Cord. If no additional Cable Ties are needed, make sure to properly reconnect any Accessory Cables that may have been disconnected.
- Bundle any excess cable in a loose loop no less than 4" in diameter. The Reusable Cable Tie can be used to secure excess cable.



> Installing the Prop

1

ITEM(S) NEEDED



#10 x 1





#13 x 1

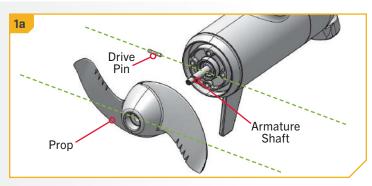
△ CAUTION

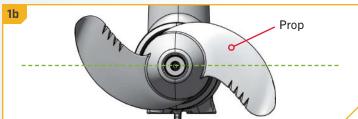
Disconnect the motor from the battery before beginning any Prop work or maintenance.

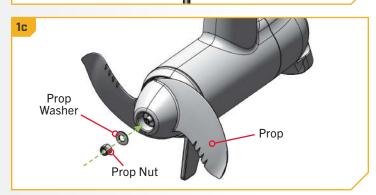
- a. Take the Drive Pin (Item #13) and slide it through the Hole in the Armature Shaft. Position the Drive Pin horizontally by grasping the Armature Shaft and rotating it with the Drive Pin in place.
- b. Align the Prop (Item #10) so it is horizontal and parallel with the Drive Pin. Slide the Prop onto the Armature Shaft and Drive Pin until it is seated against the lower unit.
- c. Install the Prop Washer (Item #11) and the Prop Nut (Item #12) onto the end of the Armature Shaft.
- d. While holding the Prop horizontal, tighten the Prop Nut with a 9/16" Deep Well Socket. Tighten the Prop Nut to 25-35 in-lbs.

△ CAUTION

Do not over-tighten as this can damage the Prop.







ONE-BOAT NETWORK

OPTIMIZING THE PERFORMANCE OF THE TERROVA QUEST WITH THE WIRELESS REMOTE OR ONE-BOAT NETWORK APP

Minn Kota® and Humminbird® have joined forces to bring you the One-Boat Network, including the latest Advanced GPS Navigation Wireless Remote and the One-Boat Network app. The Wireless Remote comes from the factory paired to the trolling motor. To learn more about Wireless Remote features, refer to the Wireless Remote Owner's Manual online at minnkota.johnsonoutdoors.com.

To get the most from your One-Boat Network, we encourage you to download the One-Boat Network app onto your smart device. The One-Boat Network® app is a free iOS and Android application that you can download to a mobile device, providing unparalleled control over all of your One-Boat Network connected products. Minn Kota recommends connecting the trolling motor to the OBN app to assist in these steps. For instructions on pairing the OBN app to the trolling motor, refer to the OBN Quick Start Guide included with the motor. For more information on the OBN app, refer to the One-Boat Network Owner's Manual online at minnkota.johnsonoutdoors.com.

Completing the installation of the Terrova QUEST through the Wireless Remote or OBN app should be done following the Prop installation. Ensure that the trolling motor is connected to a power source before adjusting One-Boat Network settings.

WARNING

Take care that neither you nor other persons approach the turning propeller too closely, neither with body parts nor with objects. The motor is powerful and may endanger or injure you or others. Stay clear of the Prop and watch out for accidental engagement.

NOTICE: Ensure that the trolling motor is connected to a power source before adjusting One-Boat Network settings.

NOTICE: If the Wireless Remote is lost or becomes nonfunctioning during navigation, and the One-Boat Network app is unavailable, press the Stow Deploy Lever at the front of the Mount to cancel all active navigation and turn off the Prop.





ONE-BOAT NETWORK ADJUSTMENTS

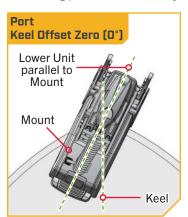
ONE-BOAT NETWORK ADJUSTMENTS >

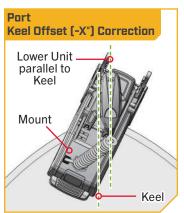
KEEL OFFSET

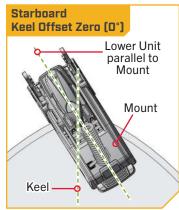
The Terrova QUEST comes from the factory with the Lower Unit parallel to the Mount. When the Lower Unit is parallel to the Mount, the Keel Offset is zero. In an ideal installation, the Lower Unit will be parallel to the Keel; however, the Mount is rarely installed to be perfectly inline with the Keel, therefore the Lower Unit will not be parallel with the Keel. Nearly all installations will have some variation in mounting position to either the Port or Starboard side

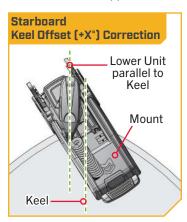
NOTICE: When the motor is installed from the factory, the Keel Offset is 0 degrees. When adjusting the Keel Offset, any position towards Port will create a Keel Offset of a negative angle. Any position towards Starboard will create a positive angle.

of the boat. The Keel Offset feature records the position of the Lower Unit when it is parallel to the Keel based on the Mount being offset from the Keel. Before adjusting the Keel Offset, complete all installation steps. This includes mounting the trolling motor to the boat and installing power and accessory cables. The Keel Offset can be recorded through the Wireless Remote or One-Boat Network App.



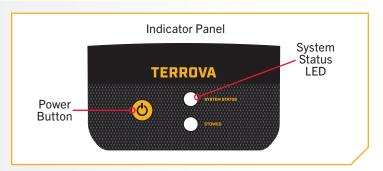


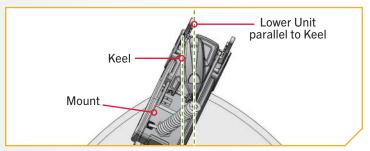




> Setting the Keel Offset with the Wireless Remote

- 1
- Power on the trolling motor by pressing the Power
 button on the Indicator Panel. When the trolling motor is on, the System Status LED will be blue.
- With either the Wireless Remote, foot pedal, or One-Boat Network (OBN) app on a paired mobile device, steer the motor so that the control head and lower unit are parallel to the Keel.



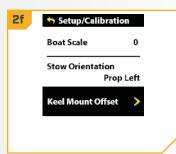


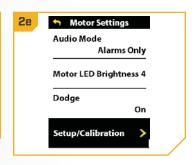
KEEL OFFSET

2

- c. Press the Menu 💽 button on the Wireless Remote.
- d. Use the Speed Up or Speed Down button to find the Motor Settings menu. Use the Steer Right button to select Motor Settings.
- e. In the Motor Settings Menu, use the Speed Up or Speed Down button to find Setup/Calibration.
- f. In the Setup/Calibration menu, use the Speed Up
 or Speed Down button to find Keel
 Mount Offset. Use the Steer Right button to select
 Keel Mount Offset.

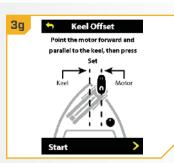


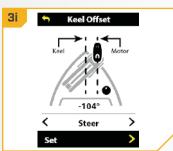


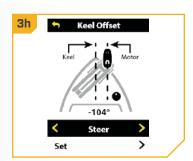


3

- g. Review all safety warnings. Use the Steer Right button to select Start and begin the process.
- h. Use the Steer Left or Steer Right button to point the motor forward and parallel to the keel.
- i. When satisfied with the placement of the trolling motor, use the Speed Up or Speed Down button to scroll to Set. Use the Steer Right button to select Set. The degree of offset is displayed at the bottom of the Dashboard.

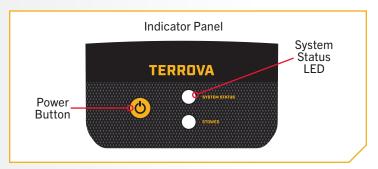


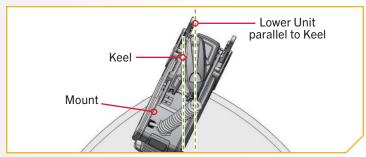




Setting the Keel Offset with the One-Boat Network App

- Power on the trolling motor by pressing the Power **button on the Indicator Panel. When the trolling** motor is on, the System Status LED will be blue.
- b. With either the Wireless Remote, foot pedal, or One-Boat Network (OBN) app on a paired mobile device, steer the motor so that the control head and lower unit are parallel to the Keel.





- c. Open the One-Boat Network (OBN) app on the mobile device. Make sure the mobile device is paired with the trolling motor.
- d. From the OBN home screen, tap the Motor menu. The Motor menu opens the Motor home screen.
- e. Before the Motor home screen will open, tap Agree on the on-screen prompt.

NOTICE: The on-screen prompt will only display once each time the app is launched. If the prompt has displayed, the Motor home screen appears.

On the Motor home screen, locate the Motor Settings button in the upper-right corner and tap it.







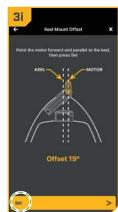
KEEL OFFSET

3

- g. In the Motor Settings menu, find and tap Setup and Calibration.
- h. In Setup and Calibration, find and tap Keel Mount Offset.
- Review all safety warnings. Follow the prompts in the One-Boat Network app. If the placement of the trolling motor is pointing forward and parallel to the keel, tap Set. The degree of offset will show at the bottom of the app Display.









- j. If the trolling motor needs to be adjusted, locate the Return button on the upper-left corner of the app screen. Tap the Return button three times until the Motor home screen displays.
- k. Use the Steer Right > and Steer Left < buttons to point the motor forward and parallel to the keel.
- When satisfied with the placement of the trolling motor, locate the Motor Settings button in the upper-right corner and tap it.
- m. In the Motor Settings menu, find and tap Setup and Calibration.
- n. In Setup and Calibration, find and tap Keel Mount Offset. If the placement of the trolling motor is pointing forward and parallel to the keel, tap Set.
- o. The degree of offset shows at the bottom of the app Display. Tap Return to close the Keel Mount Offset and return to the home screen.







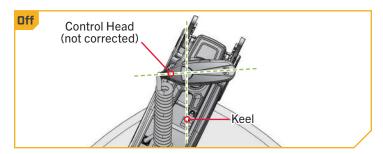


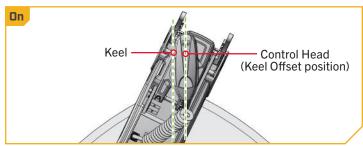


STRAIGHT ON DEPLOY

Minn Kota recommends setting the Keel Offset when the position of the Lower Unit is parallel with the Keel. Save the Keel Offset before exploring the Straight on Deploy feature. Straight on Deploy uses the position recorded in Keel Offset to know where to position the Lower Unit to be parallel with the Keel.

When Straight on Deploy is engaged, the lower unit will automatically rotate to the Keel Offset position when deployed. By default, the Lower Unit will be parallel to the Keel when the Mount is parallel to the Keel. If the Keel Offset was programmed to another angle, the Straight on Deploy feature will correct the position to match the Keel Offset angle when turned "on." If Straight on Deploy is turned "off," the trolling motor will not correct the position in any direction.

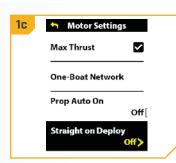




To Toggle Straight on Deploy with the Wireless Remote

- With the motor on, press the Menu 📧 button on the Wireless Remote.
- b. Use the Speed Up or Speed Down button to find the Motor Settings menu. Use the Steer Right button to select Motor Settings.
- c. In the Motor Settings Menu, use the Speed Up or Speed Down button to find Straight on Deploy.
- d. By default, the Straight on Deploy is toggled "off."
- e. Use the Steer Right button to toggle between "on" and "off."





STRAIGHT ON DEPLOY

To Toggle Straight on Deploy with the One-Boat Network App

- 1
- a. Open the One-Boat Network (OBN) app on a mobile device. Make sure the mobile device is paired with the trolling motor and that the motor is powered "on."
- b. From the OBN home screen, tap the Motor menu. The Motor menu opens the Motor home screen.
- c. Before the Motor home screen will open, tap Agree on the on-screen prompt.

NOTICE: The on-screen prompt will only display once each time the app is launched. If the prompt has displayed, the Motor home screen appears.

d. On the Motor home screen, locate the Motor Settings button in the upper-right corner and tap it.







2

e. In the Motor Settings menu, find the Straight Ahead on Deploy toggle. Tap to turn the toggle "on" and "off." When highlighted yellow the toggle is "on."



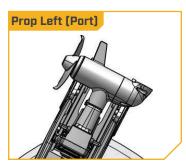


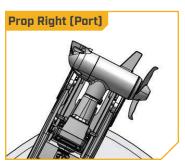
STOW ORIENTATION

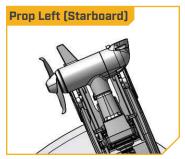
The Stow Orientation is a term used to describe the lower unit and Prop position when the motor is stowed. The lower unit will automatically rotate into the Stow Orientation when stowing the motor. The Stow Orientation can be set to Prop Left or Prop Right through the Wireless Remote or One-Boat Network app. The factory default setting for the lower unit is Prop Left. Adjusting

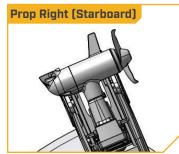
NOTICE: If the Stow Orientation is set to Prop Right, the Depth Collar must be rotated on the Shaft to improve accessibility. See the "Rotating the Depth Collar" section for instructions.

the Stow Orientation allows the installation to be customized to fit boat positioning for either a Port or Starboard installation and to accommodate fishing or trailering applications.





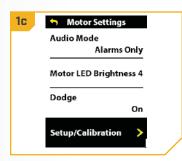




> Setting the Stow Orientation with the Wireless Remote

- With the trolling motor powered on, press the Menu button on the Wireless Remote.
- b. Use the Speed Up or Speed Down button to find the Motor Settings menu. Use the Steer Right button to select Motor Settings.
- c. In the Motor Settings Menu, use the Speed Up or Speed Down button to find Setup/Calibration. Use Steer Right to open the Setup/Calibration menu.





- d. Once in the Setup/Calibration menu, use the Speed Up or Speed Down button to find Stow Orientation. Use Steer Right to open the Stow Orientation menu.
- e. In the Stow Orientation menu, use the Speed Down or Speed Up button to scroll between Prop Left and Prop Right. Use the Steer Right 2 button to select the desired stow orientation.





STOW ORIENTATION

> Setting the Stow Orientation with the One-Boat Network App

- a. Open the One-Boat Network (OBN) app on a mobile device. Make sure the mobile device is paired with the trolling motor and that the motor is powered "on."
- b. From the OBN home screen, tap the Motor menu. The Motor menu opens the Motor home screen.
- Before the Motor home screen will open, tap Agree on the on-screen prompt.

NOTICE: The on-screen prompt will only display once each time the app is launched. If the prompt has displayed, the Motor home screen appears.

d. On the Motor home screen, locate the Motor Settings button in the upper-right corner and tap it.







- In the Motor Settings menu, find and tap Setup and Calibration.
- f. In Setup and Calibration, find and tap Stow Orientation.
- g. Set the feature to Prop Right or Prop Left.







BOAT SCALE

Trolling motor performance can be impacted by factors including, but not limited to, wind, water conditions, boat specifications, battery health, wiring, etc. Boat Scale provides a method of adjusting how the trolling motor will perform to account for these and other variables. The Terrova QUEST comes from the factory with Boat Scale set to zero. Boat Scale can be adjusted up (+2) or down (-2) to increase or decrease how the motor control software applies power while using a navigation mode like Spot-Lock.

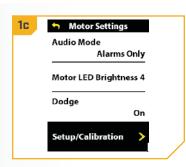
An example showing the need to reduce Boat Scale would be while using Spot-Lock and the motor is over-correcting or making frequent adjustments. In this case, try reducing Boat Scale -1 to reduce this behavior. If the behavior continues, reduce Boat Scale to -2. An example showing the need to increase Boat Scale while using Spot-Lock would be the motor is drifting away from its target location frequently or needs help to make corrections. Try increasing Boat Scale to +1 to help improve the trolling motor accuracy in this case. If the behavior continues, increase Boat Scale to +2.

Adjusting Boat Scale with the Wireless Remote



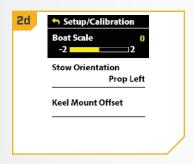
- a. With the motor on, press the Menu 💷 button on the Wireless Remote.
- b. Use the Speed Up or Speed Down button to find the Motor Settings menu. Use the Steer Right button to select Motor Settings.
- c. In the Motor Settings Menu, use the Speed Up or Speed Down button to find Setup/Calibration.







- d. Once in the Setup/Calibration menu, use the Speed Up or Speed Down button to find Boat Scale.
- e. Use the Steer Left or Steer Right button to adjust the Boat Scale to one of the five settings: -2, -1, 0, 1 or 2.



BOAT SCALE

Adjusting Boat Scale with the One-Boat Network App

- a. Open the One-Boat Network (OBN) app on a mobile device. Make sure the mobile device is paired with the trolling motor and that the motor is powered "on."
- b. From the OBN home screen, tap the Motor menu. The Motor menu opens the Motor home screen.
- c. Before the Motor home screen will open, tap Agree on the on-screen prompt.

NOTICE: The on-screen prompt will only display once each time the app is launched. If the prompt has displayed, the Motor home screen appears.

d. On the Motor home screen, locate the Motor Settings button in the upper-right corner and tap it.







- e. In the Motor Settings menu, find and tap Setup and Calibration.
- In Setup and Calibration, find and tap Boat Scale.
- g. Set the feature to increase or decrease Boat Scale.







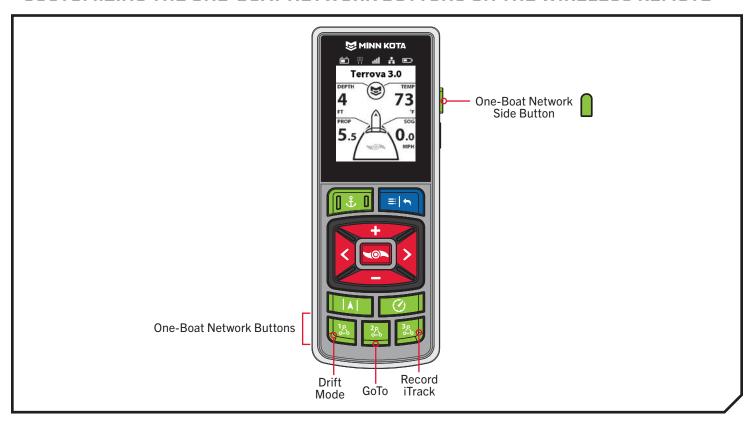
ONE-BOAT NETWORK BUTTONS

ONE-BOAT NETWORK BUTTONS >

Minn Kota trolling motors equipped with Advanced GPS Navigation are compatible with devices enabled with the One-Boat Network (OBN), such as the Wireless Remote and Foot Pedal. OBN functions can be enabled and disabled through customizable OBN buttons on the Wireless Remote and Foot Pedal. The function of the OBN buttons can be customized based on user preference to enhance operation of the OBN product. Customizable OBN buttons include:

- 1. The four One-Boat Network buttons on the Wireless Remote
- 2. The One-Boat Network button on the Foot Pedal

CUSTOMIZING THE ONE-BOAT NETWORK BUTTONS ON THE WIRELESS REMOTE



One-Boat Network Default Buttons				
126	Drift Mode	328	Record iTrack	
2 ₆ -6	GoTo		Mark a Waypoint	

CUSTOMIZING THE ONE-BOAT NETWORK BUTTONS ON THE WIRELESS REMOTE

One-Boat Network functions can be enabled and disabled through four One-Boat Network buttons on the Wireless Remote. The One-Boat Network buttons can be customized to control the following functions, depending on your setup:

Function	Icon	Description	
Drift Mode	1	Drift mode is the default function for OBN Button 1. Press once to engage Drift Mode. Press a second time to Adjust Course.	
Go To	4	Go To is the default for the OBN Button 2. Press once to open the Go To Menu. The Go To options are Spot-Locks, Waypoints, iTracks and Drift.	
Record iTrack	್ರೆಂ	Record iTrack is the default function for OBN Button 3. Press once to start recording an iTrack. Press a second time to save the iTrack.	
Waypoint	又	Mark Waypoint is the default function for the OBN Side Button. Press once to save a Waypoint.	
Max Speed	€r	Max Speed must first be customized to one of the OBN buttons. Double press to engage Max Speed. Single press to return to the previous speed.	
Talon/Raptor	Ħ	The shallow water anchor function must first be customized on one of the OBN buttons. The shallow water anchor function will display as Talon or Raptor depending on your configuration. Double press to deploy the anchor. Press once to pause or stow the anchor.	

CUSTOMIZING THE ONE-BOAT NETWORK BUTTONS ON THE WIRELESS REMOTE

Customize the One-Boat Network Buttons on the Wireless Remote



- a. On the Wireless Remote, press the Menu 🗪 button to open the Motor Menu.
- b. In the Motor Menu, use the Speed Down or Speed Up button to find the Motor Settings menu. Use the Steer Right button to select Motor Settings.
- c. In the Motor Settings menu, use the Speed Down or Speed Up button to find One-Boat Network. Use the Steer Right button to select One-Boat Network.
- d. In the One-Boat Network Menu, use the Speed Down or Speed Up button to find Remote Buttons. Use the Steer Right button to select Remote Buttons.





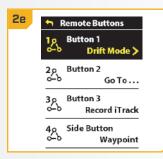




- Use the Speed Down or Speed Up button to highlight the OBN button to customize. There are four options: Button 1, Button 2, Button 3 or Side Button. Press the Steer Right button to make the selection.
- Use the Speed Down or Speed Up button to scroll through the options. Use the Steer Right button to select the function.

NOTICE: The radio button next to the desired function will be selected when the Steer Right button is used to customize the function. The function options listed are based on the trolling motor and other devices in the Advanced GPS Navigation network.

Press and hold the Menu button to close and return to the Home Screen.



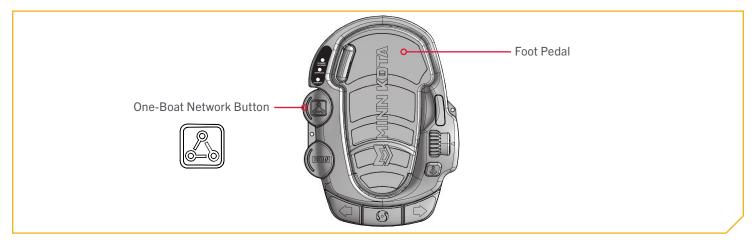


NOTICE: For quick customization, press and hold the OBN button you want to customize to quickly bring up the customization screen.

CUSTOMIZING THE ONE-BOAT NETWORK BUTTON ON THE FOOT PEDAL

CUSTOMIZING THE ONE-BOAT NETWORK BUTTON ON THE FOOT PEDAL

Minn Kota trolling motors equipped with Advanced GPS Navigation are compatible with devices enabled with the One-Boat Network, such as the Foot Pedal. One-Boat Network functions are enabled and disabled through the Foot Pedal with the One-Boat Network & button. This button can be customized using either the Wireless Remote or the One-Boat Network app on a paired mobile device.



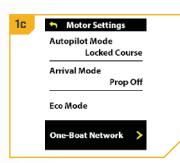
The One-Boat Network 🕰 button on the Foot Pedal can be customized to control the following functions:

Function	Operation	LED Indication
AutoPilot (default)	Engage and disengage AutoPilot	Red LED will illuminate when AutoPilot is engaged and stay on until disengaged.
Waypoint	Mark a Waypoint	Red LED will illuminate when the One-Boat Network button is pressed and then turn off, signaling that a Waypoint was marked.
Shallow Water Anchor (Raptor/Talon)	Deploy and retract a Raptor/Talon	Red LED will steadily flash when the Shallow Water Anchor is deploying or stowing. Red LED will stay illuminated when the anchor is at any state of deployment, including when it is paused. Red LED will turn off when the anchor is fully stowed.

Customize the OBN Button on the Foot Pedal with the Wireless Remote

- 1
- a. With the trolling motor powered on, press the Menu button on the Wireless Remote.
- In the Motor Menu, use the Speed Down or Speed Up button to find the Motor Settings menu. Use the Steer Right button to select Motor Settings.
- c. In the Motor Settings menu, use the Speed Down or Speed Up button to find One-Boat Network. Use the Steer Right button to select One-Boat Network.





CUSTOMIZING THE ONE-BOAT NETWORK BUTTON ON THE FOOT PEDAL

- In the One-Boat Network menu, use the Speed Down or Speed Up button to find Foot Pedal. Use the Steer Right button to select Foot Pedal.
- In the Foot Pedal menu, use the Speed Down or Speed Up button to find the desired function. Use the Steer Right button to select
- Press and hold the Menu button to close and return to the Home Screen.





NOTICE: The radio button next to the desired function will be selected when the Steer Right 💆 button is used to customize the function. AutoPilot is the default selection for Terrova QUEST trolling motors. The function options listed are based on the trolling motor and other devices in the Advanced GPS Navigation network.

Customize the OBN Button on the Foot Pedal with the One-Boat Network App

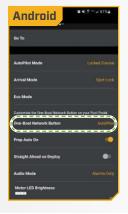
- a. Open the One-Boat Network (OBN) app on a mobile device. Make sure the mobile device is paired with the trolling motor and that the motor is powered "on."
- b. From the OBN home screen, tap the Motor menu. The Motor menu opens the Motor home screen.
- c. Before the Motor home screen will open, tap Agree on the on-screen prompt.
- d. On the Motor home screen, locate the Motor Settings button in the upper-right corner and tap it.







- On an Android: in the Motor Settings menu, locate "One-Boat Network Button" and tap it.
- On iOS: in the Motor Settings menu, locate Foot Pedal and tap it.
- g. Tap the desired function. The radio button next to the selected function will be highlighted.



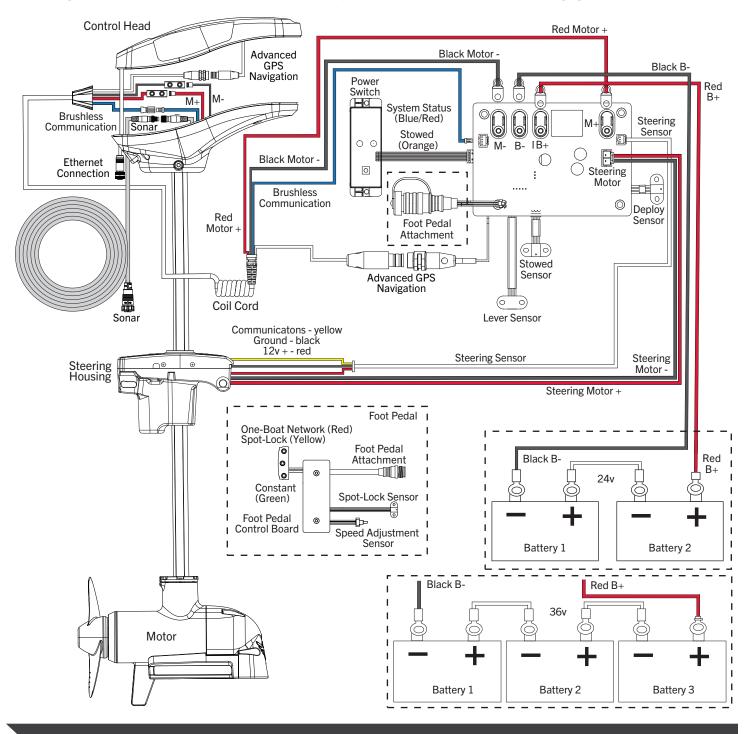




MOTOR WIRING DIAGRAM

TERROVA QUEST

The following Motor Wiring Diagram applies to all QUEST series Terrova trolling motor models that come factory installed with Advanced GPS Navigation, a Foot Pedal and Sonar. Sonar is either Dual Spectrum CHIRP or Built-in MEGA Side Imaging.

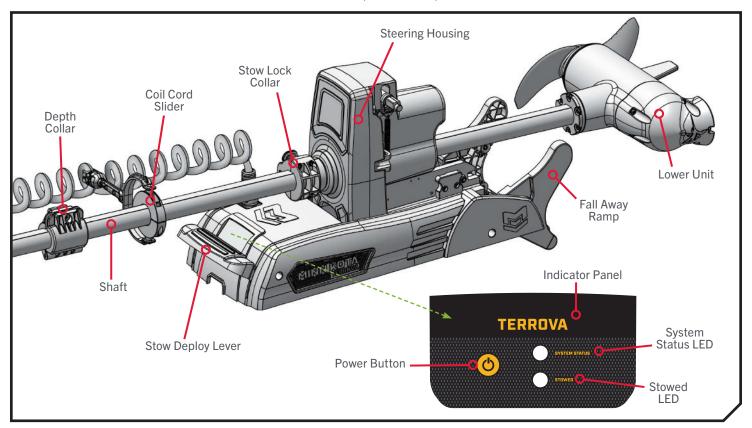


NOTICE: This is a multi-voltage diagram. Double-check your motor's voltage for proper connections. Over-Current Protection Devices are not shown in this illustration.

USING & ADJUSTING THE MOTOR

MOUNT FEATURES

Become familiar with the features of the motor to maximize the capabilities this product offers.



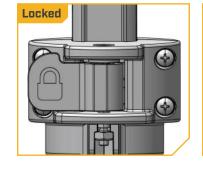
Depth Collar

The Depth Collar functions to hold the motor at the proper depth while deployed. On motors with a shaft length of 45" or 60", the Depth Collar also holds the motor in place when stowed. Open the Cam Lever to release the Depth Collar and allow it to slide up and down the motor Shaft. Close the Cam Lever to secure the Depth Collar in place. On motors with a shaft length of 45" or 60", the Depth Collar sits between the Control Head and Steering Housing. On motors with a 72" shaft length, the Depth Collar sits between the Control Head and the Coil Cord Slider.

Stow Lock Collar

On motors with a shaft length of 72", a Stow Lock Collar sits above the Steering Housing and functions to hold the motor in place when stowed. The Stow Lock Collar is not present on motors with a shaft length of 45" or 60". The Stow Lock Collar is stationary and can be locked to secure the Shaft or unlocked to allow the Shaft to slide freely when stowing or deploying. Flip the Lock Arm to lock or unlock the Stow Lock Collar.

Each side of the Lock Arm has an icon that displays the status of the Stow Lock Collar. When the Lock Picon is visible, the Stow





Lock Collar is locked and the Shaft is secure; when the Unlock 🖺 icon is visible, the Stow Lock Collar is unlocked and will not hold the Shaft in place. When locking or unlocking, be sure to press the Lock Arm so that it is fully seated against the Stow Lock Collar.

MOUNT FEATURES

⚠ WARNING

When the motor is being transported, it is important to fully lock the Stow Lock Collar (for shaft lengths 72") or secure the Depth Collar snug against the Steering Housing (for shaft lengths 45" or 60"). This provides a secure stow and holds the motor in place during transportation when it is subject to high levels of shock and vibration. Failure to secure the motor may result in injury or damage to the unit.

Coil Cord Slider

Motors with a shaft length of 72" have a Coil Cord Slider. The Coil Cord Slider functions to support the Coil Cord and prevent it from becoming tangled or hitting obstructions. The Coil Cord Slider sits on the Shaft between the Stow Lock Collar and the Depth Collar. The arm of the Coil Cord Slider connects to the Coil Cord. The Coil Cord Slider floats freely on the Shaft and moves with the Coil Cord while stowing and deploying.

> Fall Away Ramps

The Fall Away Ramps hold and support the Lower Unit when the motor is in the stowed position. The Fall Away Ramps also rotate to release the Lower Unit when deployed and guide the Lower Unit back onto the mount when stowed. When the Fall Away Ramps latch into an upright position, the STOWED LED on the Indicator Panel will illuminate orange. The position of the Fall Away Ramps is released for deployment by pressing the Stow Deploy Lever.

▲ WARNING

When stowing or deploying the motor, keep fingers clear of all hinge and pivot points and all moving parts.

NOTICE: The appearance of the Fall Away Ramps varies based on sonar type.

Stow Deploy Lever

The Stow Deploy Lever functions to unlatch the Fall Away Ramps and release the motor for deploying or stowing. When the motor is in the deployed position, pressing the Stow Deploy Lever will cause the Lower Unit to automatically rotate into the Stow Orientation. The Stow Deploy Lever is located at the front of the mount and is activated by pressing the Lever down.

△ CAUTION

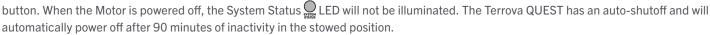
For safety reasons, disconnect the motor from the battery/batteries when the motor is not in use or while the battery/batteries are being charged. If the motor control is left on and the propeller rotation is blocked, severe motor damage can result.

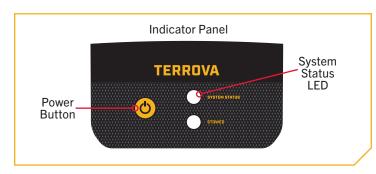
INDICATOR PANEL

The Indicator Panel is located at the front of the Mount, above the Stow Deploy Lever. Power to the motor is turned "on" and "off" through the Power button on the Indicator Panel. The LEDs on the Indicator Panel communicate the status of the motor.

Power Button

The Terrova QUEST must be manually powered "on" and "off." Press the Power **b** button on the Indicator Panel to turn the motor "on." When the motor is powered on, the System Status LED will illuminate blue. To turn the motor "off," press and release the Power





LED Patterns

STOWED

 Orange solid — Indicates that the trolling motor is stowed. The Fall Away Ramps are locked upright to support the Lower Unit. When the motor is deployed, the STOWED LED will not be illuminated.

SYSTEM STATUS

- Blue solid Normal operation. The trolling motor is powered on. When the Motor is powered off, the System Status LED will not be illuminated.
- Red flashing Critical error. The Prop will lock so that it cannot be engaged. A critical error must be manually cleared by correcting the source of the error. Once fixed, cycle power to the trolling motor by pressing the Power button "off" and then back "on" to clear the error and resume normal operation.

▲ WARNING

The trolling motor is not safely stowed for transport until the orange STOWED O LED is illuminated and the Stow Lock Collar is locked or the Depth Collar is secured against the Steering Housing.

NOTICE: When encountering a critical error, the Wireless Remote will provide an error code in the Diagnostic menu. Refer to the Wireless Remote Owner's Manual to learn more about error codes.

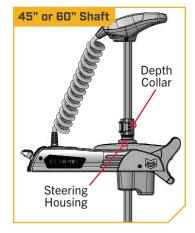
STOWING AND DEPLOYING THE MOTOR

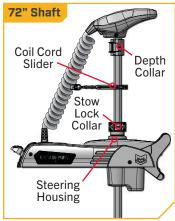
STOWING AND DEPLOYING THE MOTOR

The method for securely stowing and deploying the Terrova QUEST varies slightly between short-shaft and long-shaft motors.

Short-shaft motors have shaft lengths of 45" or 60". Motors with a short shaft only have a Depth Collar, which is used to set the motor depth when deploying. When stowing the motor, the Depth Collar is placed against the Steering Housing to ensure a secure stow.

Long-shaft motors have a shaft length of 72". Motors with a long shaft contain a Stow Lock Collar, Coil Cord Slider and Depth Collar. On long-shaft motors, the Depth Collar functions to hold the motor at the proper depth when deployed. The Stow Lock Collar is





unlocked to allow the Shaft to move freely when stowing and deploying. After stowing the motor, the Stow Lock Collar is locked to ensure a secure stow. The Stow Lock Collar can also be locked to hold the motor at the proper depth when deployed in shallow water.

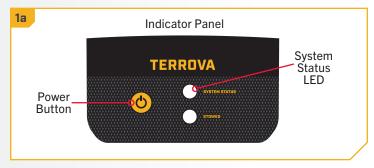
45" AND 60" SHAFTS >

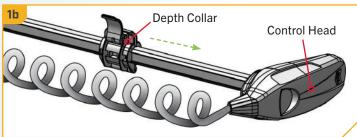
To Deploy the Motor (45" and 60" Shafts)

- 1
- a. Power on the trolling motor by pressing the Power
 button on the Indicator Panel. When the trolling motor is on, the System Status LED will be blue.
- b. Release the Depth Collar by opening the Cam Lever. Slide the Depth Collar up towards the Control Head. When at the desired depth, close the Cam Lever to lock the Depth Collar position on the Shaft.

▲ WARNING

When stowing or deploying the motor, keep fingers clear of all hinge and pivot points and all moving parts.





TO DEPLOY THE MOTOR (45" AND 60" SHAFTS)

Firmly grasp the Shaft or Control Head above the Depth Collar, then press the Stow Deploy Lever at the base of the mount to release the Fall Away Ramps.

▲ WARNING

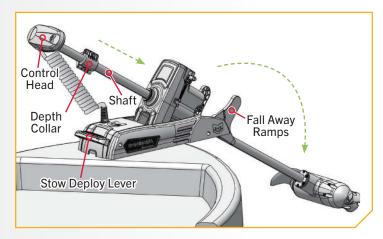
The Control Head will create a pinch point if the Depth Collar is released and the Control Head slides to the top of the Depth Collar. Grasp the Shaft to prevent it from sliding all the way down and creating a pinch point.

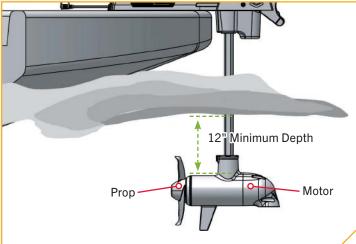
Practice proper ergonomics when stowing and deploying the motor to prevent injury.

△ CAUTION

If the Keel Offset has been configured, and Straight On Deploy is toggled "on," the motor will automatically rotate into the Keel Offset position when the Shaft is fully vertical and the Steering Housing locks into the deployed position. Be aware of this motion to avoid suddenly releasing the Shaft and to avoid contacting pinch points.

d. Guide the Lower Unit out and away from the Fall Away Ramps. Maintain a secure hold while guiding the motor to the deployed position. Allow the Lower Unit to drop and tilt so that the Shaft is vertical. Lower the motor into the water until the Depth Collar is seated against the Steering Housing.





NOTICE: Ensure that the top of the lower unit is submerged at least 12" below the surface of the water to avoid churning or agitation of surface water.

TO STOW THE MOTOR (45" AND 60" SHAFTS)

To Stow the Motor (45" and 60" Shafts)



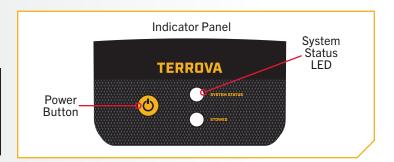
a. Power on the trolling motor by pressing the Power
 button on the Indicator Panel. When the trolling motor is on, the System Status LED will be blue.

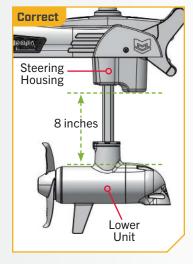
▲ WARNING

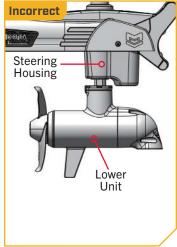
When stowing or deploying the motor, keep fingers clear of all hinge and pivot points and all moving parts.

NOTICE: Leave no less than 8" of space between the bottom of the Steering Housing and the top of the Lower Unit when tilting the motor into the stowed position. If the Lower Unit is trimmed too high before tilting the motor, the Lower Unit will collide with the Mount and be unable to stow.

NOTICE: When stowing the motor, ensure that the area between the Mount and Steering Housing is clean and free of debris. The Mount contains pads that contact the Steering Housing when stowed. The motor cannot stow securely if an obstruction is present on the pads.







TO STOW THE MOTOR (45" AND 60" SHAFTS)

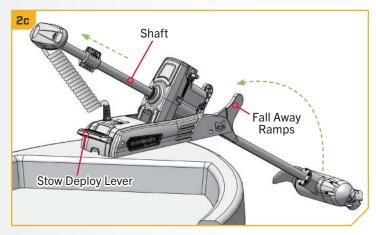
2

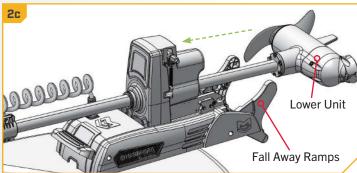
- b. Press the Stow Deploy Lever at the front of the mount. This will cause the Shaft and Lower Unit to automatically rotate into the Stow Orientation. Allow the Lower Unit to complete this motion before stowing the motor.
- c. Grasp the Shaft or Control Head. While holding down the Stow Deploy Lever, pull the Shaft upward to raise the Lower Unit. Tilt the Shaft into a horizontal position while guiding the motor toward the Fall Away Ramps. Pull the Lower Unit fully onto the Ramps. The Fall Away Ramps will latch upright and the STOWED LED on the Indicator Panel will illuminate orange when the motor is properly stowed.
- d. Open the Cam Lever on the Depth Collar and slide it down the Shaft until it is seated against the Steering Housing. Close the Cam Lever on the Depth Collar to secure the motor in the stowed position.

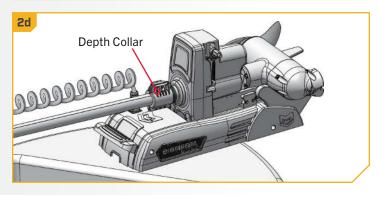
NOTICE: The trolling motor is not safely stowed for transport until the orange STOWED LED is illuminated, the Fall Away Ramps are latched upright with the Lower Unit in place, and the Depth Collar is secured against the Steering Housing.

△ WARNING

When the motor is stowed, the Depth Collar must be placed against the Steering Housing and secured with the Cam Lever closed to prevent accidental deployment. Accidental deployment may result in injury or damage to the trolling motor, accessories, or boat.







TO DEPLOY THE MOTOR (72" SHAFTS)

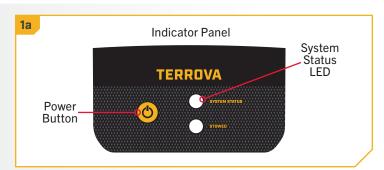
72" SHAFTS >

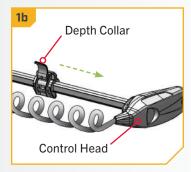
To Deploy the Motor (72" Shafts)

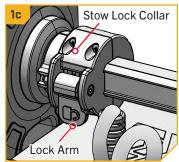
- 1
- a. Power on the trolling motor by pressing the Power
 button on the Indicator Panel. When the trolling motor is on, the System Status LED will be blue.
- Release the Depth Collar by opening the Cam Lever.
 Slide the Depth Collar up towards the Control Head.
 When at the desired depth, close the Cam Lever to lock the Depth Collar position on the Shaft.
- c. Unlock the Stow Lock Collar by flipping the Lock Arm to the unlocked position. Be sure to press the Lock Arm so that it is fully seated. The Stow Lock Collar must be completely unlocked so the Shaft can slide freely.

▲ WARNING

When stowing or deploying the motor, keep fingers clear of all hinge and pivot points and all moving parts.







TO DEPLOY THE MOTOR (72" SHAFTS)

Firmly grasp the Shaft or Control Head above the Depth Collar, then press the Stow Deploy Lever at the base of the mount to release the Fall Away Ramps.

▲ WARNING

The spaces between the Depth Collar, Coil Cord Slider, and Stow Lock Collar can create pinch points. Do not come into contact with an area that may cause a pinch point when it is moving in any direction to avoid risk.

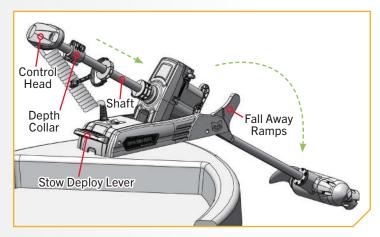
The Control Head will create a pinch point if the Control Head slides to the top of the Depth Collar, Grasp the Shaft to prevent it from sliding all the way down and creating a pinch point.

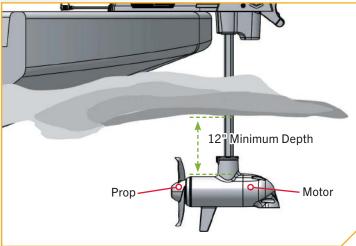
Practice proper ergonomics when stowing and deploying the motor to prevent injury.

△ CAUTION

If the Keel Offset has been configured, and Straight On Deploy is toggled "on," the motor will automatically rotate into the Keel Offset position when the Shaft is fully vertical and the Steering Housing locks into the deployed position. Be aware of this motion to avoid suddenly releasing the Shaft and to avoid contacting pinch points.

d. Guide the Lower Unit out and away from the Fall Away Ramps. Maintain a secure hold while guiding the motor to the deployed position. Allow the Lower Unit to drop and tilt so that the Shaft is vertical. Lower the motor into the water until the Depth Collar reaches the Steering Housing.





NOTICE: Ensure that the top of the lower unit is submerged at least 12" below the surface of the water to avoid churning or agitation of surface water.

TO STOW THE MOTOR (72" SHAFTS)

To Stow the Motor (72" Shafts)

- 1
- a. Power on the trolling motor by pressing the Power
 button on the Indicator Panel. When the trolling motor is on, the System Status LED will be blue.
- b. Ensure that the Stow Lock Collar is in the unlocked

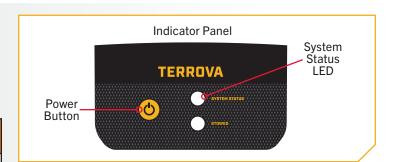
 ☐ position.

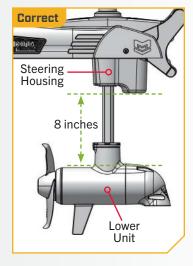
⚠ WARNING

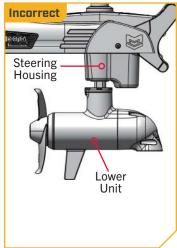
When stowing or deploying the motor, keep fingers clear of all hinge and pivot points and all moving parts.

NOTICE: Leave no less than 8" of space between the bottom of the Steering Housing and the top of the Lower Unit when tilting the motor into the stowed position. If the Lower Unit is trimmed too high before tilting the motor, the Lower Unit will collide with the Mount and be unable to stow.

NOTICE: When stowing the motor, ensure that the area between the Mount and Steering Housing is clean and free of debris. The Mount contains pads that contact the Steering Housing when stowed. The motor cannot stow securely if an obstruction is present on the pads.







TO STOW THE MOTOR (72" SHAFTS)

2

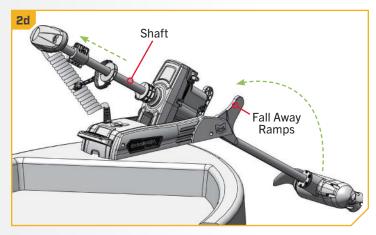
c. Press the Stow Deploy Lever at the front of the mount. This will cause the Shaft and Lower Unit to automatically rotate into the Stow Orientation. Allow the Lower Unit to complete this motion before stowing the motor.

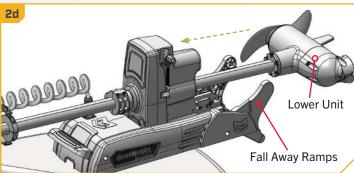
- d. Grasp the Shaft or Control Head. While holding down the Stow Deploy Lever, pull the Shaft upward to raise the Lower Unit. Tilt the Shaft into a horizontal position while guiding the motor toward the Fall Away Ramps. Pull the Lower Unit fully onto the Ramps. The Fall Away Ramps will latch upright and the STOWED LED on the Indicator Panel will illuminate orange when the motor is properly stowed.
- e. Secure the motor in place by flipping the Lock Arm on the Stow Lock Collar into the locked Position. Ensure that the Lock Arm is fully seated against the Stow Lock Collar.

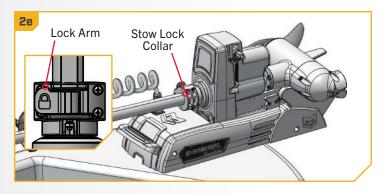
NOTICE: The trolling motor is not safely stowed for transport until the orange STOWED <u>□</u> LED is illuminated, the Fall Away Ramps are latched upright with the Lower Unit in place, and the Stow Lock Collar is locked <u>□</u>.

△ WARNING

When the motor is stowed, the Stow Lock Collar must be in the locked position to prevent accidental deployment. Accidental deployment may result in injury or damage to the trolling motor, accessories, or boat.







STOWING AND DEPLOYING IN SHALLOW WATER

STOWING AND DEPLOYING IN SHALLOW WATER

For trolling motors with a 72" shaft, the Stow Lock Collar will be required to secure the Shaft when deployed in shallow water. Due to the position of the Coil Cord Slider, the Depth Collar cannot be placed beyond the midpoint of the Shaft to hold the depth of the lower unit when deploying in shallow water. The Stow Lock Collar should be used instead to perform this function.

NOTICE: Straining against the Coil Cord Slider to place the Depth Collar too low on the Shaft may cause stress or excessive force on trolling motor components.

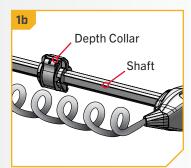
Deploying in Shallow Water (72" Shafts)

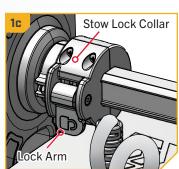


- a. Power on the trolling motor.
- b. Ensure that the Depth Collar is secured on the Shaft and will not slide around while deploying.
- c. Unlock the Stow Lock Collar by flipping the Lock Arm to the unlocked \bigcirc position.

▲ WARNING

When stowing or deploying the motor, keep fingers clear of all hinge and pivot points and all moving parts.





2

△ WARNING

The spaces between the Depth Collar, Coil Cord Slider, and Stow Lock Collar can create pinch points. Do not come into contact with an area that may cause a pinch point when it is moving in any direction to avoid risk.

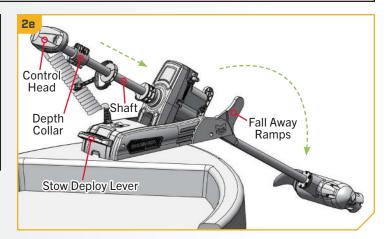
The Control Head will create a pinch point if the Control Head slides to the top of the Depth Collar. Grasp the Shaft to prevent it from sliding all the way down and creating a pinch point.

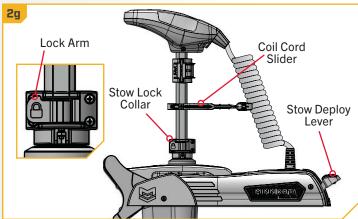
Practice proper ergonomics when stowing and deploying the motor to prevent injury.

△ CAUTION

If the Keel Offset has been configured, and Straight On Deploy is toggled "on," the motor will automatically rotate into the Keel Offset position when the Shaft is fully vertical and the Steering Housing locks into the deployed position. Be aware of this motion to avoid suddenly releasing the Shaft and to avoid contacting pinch points.

- d. Firmly grasp the Shaft or Control Head, then press the Stow Deploy Lever at the base of the mount to release the Fall Away Ramps.
- e. Guide the Lower Unit out and away from the Fall Away Ramps. Maintain a secure hold while guiding the motor to the deployed position. Allow the Lower Unit to drop and tilt so that the Shaft is vertical.
- f. Lower the motor to the desired depth.
- g. While holding the motor at the proper depth, lock the Stow Lock Collar to secure the motor. Be sure to press the Lock Arm so that it is fully seated against the Stow Lock Collar.





STOWING AND DEPLOYING IN SHALLOW WATER

> Stowing in Shallow Water (72" Shafts)

1

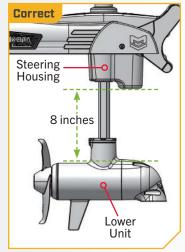
△ WARNING

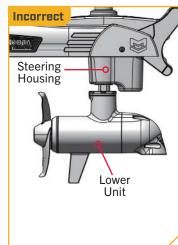
When stowing or deploying the motor, keep fingers clear of all hinge and pivot points and all moving parts.

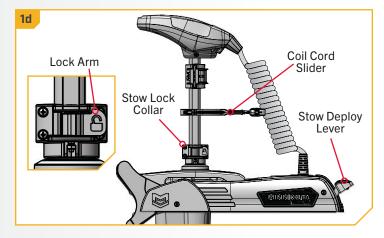
NOTICE: Leave no less than 8" of space between the bottom of the Steering Housing and the top of the Lower Unit when tilting the motor into the stowed position. If the Lower Unit is trimmed too high before tilting the motor, the Lower Unit will collide with the Mount and be unable to stow.

NOTICE: When stowing the motor, ensure that the area between the Mount and Steering Housing is clean and free of debris. The Mount contains pads that contact the Steering Housing when stowed. The motor cannot stow securely if an obstruction is present on the pads.

- a. Power on the trolling motor.
- Press the Stow Deploy Lever at the front of the mount. This will cause the Shaft and Lower Unit to automatically rotate into the Stow Orientation.
 Allow the Lower Unit to complete this motion before stowing the motor.
- c. Firmly grasp the Shaft or Control Head. Maintain a secure hold throughout the entire stowing process.
- d. Unlock the Stow Lock Collar by flipping the Lock Arm to the unlocked \bigcirc position.





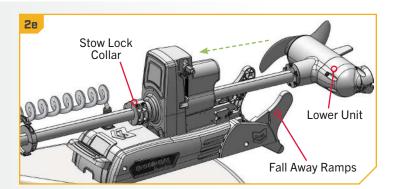


STOWING AND DEPLOYING IN SHALLOW WATER

- While holding down the Stow Deploy Lever, pull the Shaft upward to raise the Lower Unit. Tilt the Shaft into a horizontal position while guiding the motor toward the Fall Away Ramps. Pull the Lower Unit fully onto the Ramps. The Fall Away Ramps will latch upright and the STOWED

 LED on the Indicator Panel will illuminate orange when the motor is properly stowed.
- f. Secure the motor in place by flipping the Lock Arm on the Stow Lock Collar into the locked position. Ensure that the Lock Arm is fully seated against the Stow Lock Collar.

NOTICE: The trolling motor is not safely stowed for transport until the orange STOWED LED is illuminated, the Fall Away Ramps are latched upright with the Lower Unit in place, and the Stow Lock Collar is locked △.



WARNING

When the motor is stowed, the Stow Lock Collar must be in the locked position to prevent accidental deployment. Accidental Deployment may result in injury or damage to the trolling motor, accessories, or boat.

MOTOR ADJUSTMENTS

MOTOR ADJUSTMENTS

ADJUSTING THE DEPTH OF THE MOTOR

Once the boat is on the water, it may be necessary to adjust the Lower Unit up or down to achieve an optimum depth for motor performance. When setting the depth of the motor, be sure the top of the motor is submerged at least 12" below the surface of the water to avoid churning or agitation of surface water.

> Adjusting the Depth of the Motor (45" and 60" Shafts)

1

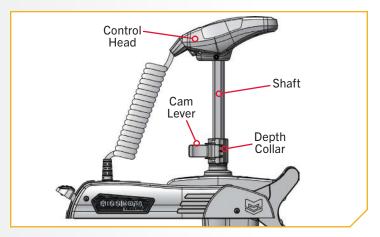
a. With the motor in the deployed position, firmly grasp the Shaft or Control Head. Maintain a secure hold throughout the entire adjustment.

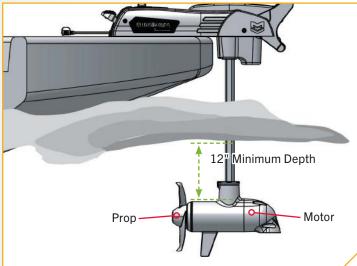
⚠ WARNING

The Control Head will create a pinch point if the Depth Collar is released and the Control Head slides to the top of the Depth Collar. Grasp the Shaft to prevent it from sliding all the way down and creating a pinch point.

- b. Lift up on the Shaft, then release the Depth Collar by opening the Cam Lever.
- c. Raise or lower the motor to the desired depth.
- d. Place the Depth Collar against the Steering Housing and close the Cam Lever to lock the Depth Collar and secure the Shaft.

NOTICE: Ensure that the top of the lower unit is submerged at least 12" below the surface of the water to avoid churning or agitation of surface water.





ADJUSTING THE DEPTH OF THE MOTOR

Adjusting the Depth of the Motor (72" Shafts)



With the motor in the deployed position, firmly grasp the Shaft or Control Head. Maintain a secure hold throughout the entire adjustment.

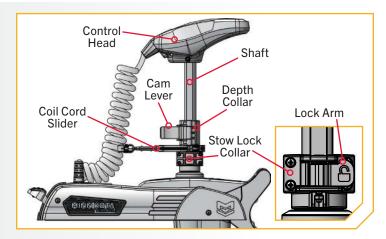
▲ WARNING

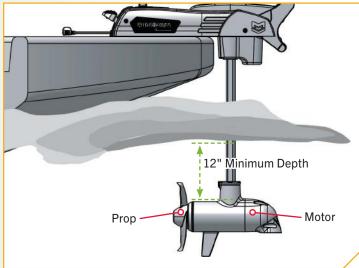
The spaces between the Depth Collar, Coil Cord Slider, and Stow Lock Collar can create pinch points. Avoid contacting an area that may cause a pinch point when it is moving in any direction to avoid risk.

The Control Head will create a pinch point if the Control Head slides to the top of the Depth Collar. Grasp the Shaft to prevent it from sliding all the way down and creating a pinch point.

Practice proper ergonomics when stowing and deploying the motor to prevent injury.

- b. Lift up on the Shaft, then release the Depth Collar by opening the Cam Lever.
- c. Ensure that the Stow Lock Collar is in the unlocked A position.
- d. Raise or lower the motor to the desired depth.
- e. Place the Depth Collar down as far as it will go against the Coil Cord Slider and Stow Lock Collar on the Steering Housing. Close the Cam Lever to lock the Depth Collar and secure the Shaft.
- If deployed in shallow water, and the Depth Collar cannot be placed beyond the Coil Cord Slider to secure the Shaft, lock the Stow Lock Collar to secure the Shaft at the proper depth.





NOTICE: Ensure that the top of the lower unit is submerged at least 12" below the surface of the water to avoid churning or agitation of surface water.

ADJUSTING THE LOWER UNIT FOR A SECURE STOW

ADJUSTING THE LOWER UNIT FOR A SECURE STOW

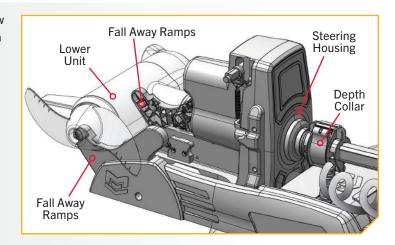
When the Motor is stowed, the Lower Unit should rest on the Fall Away Ramps. It is recommended to secure the motor using the following instructions to avoid damage to the motor and Shaft from vibrations during transport.

> Adjusting the Lower Unit for a Secure Stow (45" and 60" Shafts)

- 1
- a. Before transporting the boat over water or land, stow the motor to ensure the Lower Unit rests properly on the Fall Away Ramps. When stowing the motor, the Lower Unit should be pulled fully onto the Fall Away Ramps, which rotate up to cradle the Lower Unit in the stowed position. The STOWED LED on the Indicator Panel will illuminate orange when the Fall Away Ramps latch upright.
- If the Lower Unit does not sit on the Fall Away
 Ramps, press the Stow Deploy Lever and adjust the motor to allow the Lower Unit to rest on the Ramps.
- c. With the Lower Unit in place on the Ramps, and the orange STOWED LED illuminated on the Indicator Panel, slide the Depth Collar down against the Steering Housing and close the Cam Lever to secure the motor.

△ CAUTION

The Lower Unit should be placed on the Fall Away Ramps every time the motor is transported. If the Lower Unit is improperly placed, damage to the Lower Unit or Shaft will occur. Failure to follow the recommended placement for the Lower Unit will cause damage to the product and void your product warranty.



NOTICE: To secure the motor in place and prevent accidental deployment when stowed, slide the Depth Collar down against the top of the Steering Housing and close the Cam Lever to lock the Depth Collar.

⚠ WARNING

When the motor is being transported, it is important to place the Depth Collar snug against the Steering Housing and close the Cam Lever to lock the Depth Collar. This provides a secure stow and holds the motor in place during transportation when it is subject to high levels of shock and vibration. Failure to secure the motor may result in injury or damage to the unit.

ADJUSTING THE LOWER UNIT FOR A SECURE STOW

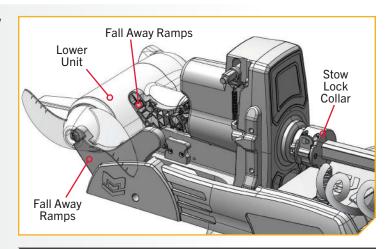
➤ Adjusting the Lower Unit for a Secure Stow (72" Shafts)

- Before transporting the boat over water or land, stow the motor to ensure the Lower Unit rests properly on the Fall Away Ramps. When stowing the motor, the Lower Unit should be pulled fully onto the Fall Away Ramps, which rotate up to cradle the Lower Unit in the stowed position. The STOWED O LED on the Indicator Panel will illuminate orange when the Fall Away Ramps latch upright.
- b. If the Lower Unit does not sit on the Fall Away Ramps, press the Stow Deploy Lever and adjust the motor to allow the Lower Unit to rest on the Ramps.
- c. With the Lower Unit in place on the Ramps, and the orange STOWED

 LED illuminated on the Indicator Panel, secure the motor in place by flipping the Lock Arm on the Stow Lock Collar into the locked position. Ensure that the Lock Arm is fully seated against the Stow Lock Collar.

△ CAUTION

The Lower Unit should be placed on the Fall Away Ramps every time the motor is transported. If the Lower Unit is improperly placed, damage to the Lower Unit or Shaft will occur. Failure to follow the recommended placement for the Lower Unit will cause damage to the product and void your product warranty.



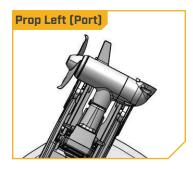
NOTICE: To secure the motor in place and prevent accidental deployment when stowed, lock the Stow Lock Collar (a). Be sure to press the Lock Arm so that it is fully seated against the Stow Lock Collar.

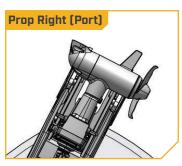
WARNING

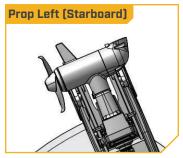
When the motor is being transported, it is important to fully lock the Stow Lock Collar. This provides a secure stow and holds the motor in place during transportation when it is subject to high levels of shock and vibration. Failure to secure the motor may result in injury or damage to the unit.

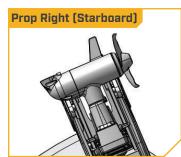
ROTATING THE DEPTH COLLAR

The Depth Collar is installed from the factory so that the Cam Lever opens in an upward motion when the Stow Orientation of the lower unit is Prop Left. The factory default Stow Orientation is Prop Left. Stow Orientation can be changed to Prop Right using the wireless remote or One-Boat Network app. For more information about Stow Orientation, refer to the "One-Boat Network" section of this manual.

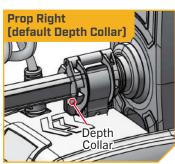


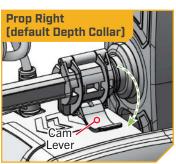




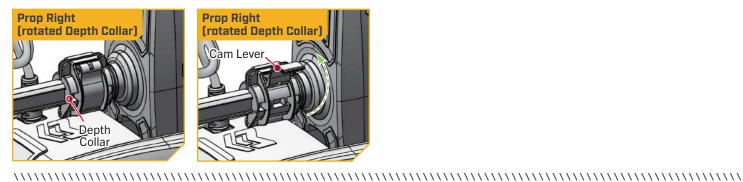


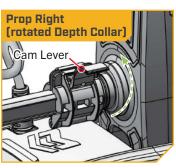
A Prop Right orientation turns the lower unit and shaft when stowed, causing the Depth Collar to open downward. This reduces its range of motion and creates an obstruction when placing the Depth Collar for a secure stow.





If the Stow Orientation is changed to Prop Right, the Depth Collar must be rotated on the shaft to improve accessibility. The Depth Collar is positioned correctly on the Shaft when the Cam Lever opens upward when the motor is stowed.





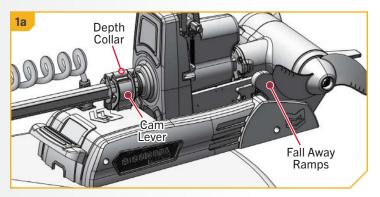
TOOLS AND RESOURCES REQUIRED >

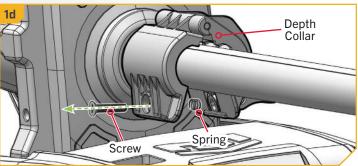
#3 Phillips Screwdriver

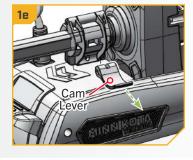
INSTALLATION >

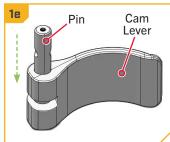
- 1
- a. With the Stow Orientation set to Prop Right, stow the trolling motor. Ensure that the Lower Unit is resting securely on the Fall Away Ramps and that the STOWED ____ LED on the Indicator Panel is illuminated orange.

- b. Release the Depth Collar by opening the Cam Lever.
- c. Locate the single Screw on the back side of the Depth Collar. This Screw secures the Cam Lever.
- d. Using a #3 Phillips Screwdriver, and with the Cam Lever open, remove the Screw from the Depth Collar. While loosening the Screw, gently open the halves of the Depth Collar to access a Spring inside. This Spring sits between the Depth Collar halves and is retained by the Screw. Take the Spring and place it onto the Screw, then set both aside for reassembly later.
- e. Remove the Cam Lever from the Depth Collar and set it aside. There is a Pin contained in the Cam Lever. If the Pin slides out, place it back in before reassembly.



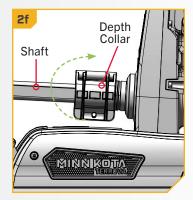


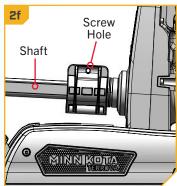


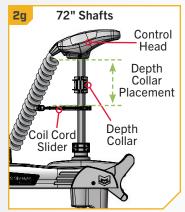


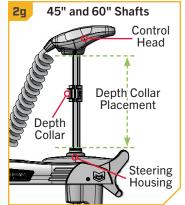
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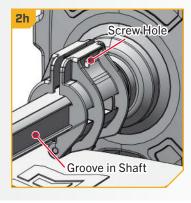
- f. Remove the Depth Collar from the Shaft. Turn the Depth Collar 180° so that the screw hole in the Depth Collar sits above the Shaft.
- g. Place the Depth Collar on the Shaft in the new position. For motors with a 72" shaft, the Depth Collar should sit between the Control Head and Coil Cord Slider. On motors with a 45" or 60" shaft, the Depth Collar can sit anywhere between the Control Head and Steering Housing.
- h. Pay attention to the shape of the Depth Collar halves and ensure that they close correctly around the Shaft. The Friction Pad inside the Depth Collar should sit against the groove of the Shaft.

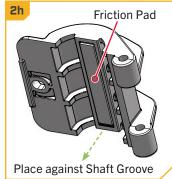






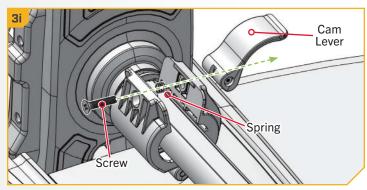


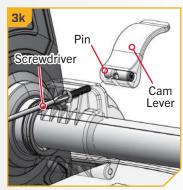


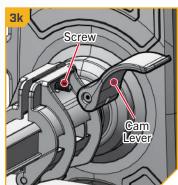


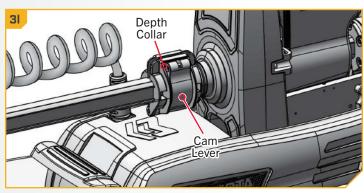
3

- With the Depth Collar in position on the Shaft, take the Screw and Spring that were removed earlier in the installation. Hold the Spring inside the Depth Collar against the screw hole. The Spring should sit between the Depth Collar halves. Insert the Screw into the Depth Collar so that it passes through the Spring and out the second half of the Depth Collar.
- j. Take the Cam Lever and ensure that the Pin is inside. Hold the Cam Lever in position against the Depth Collar, with the threaded hole in the Pin positioned towards the Screw. Pay attention to the shape of the Cam Lever and hold it so it curves over to wrap around the Depth Collar. When positioned correctly, the curve in the Cam Lever should follow the shape of the Depth Collar when closed. Attaching the Cam Lever upside down will prevent the Depth Collar from closing.
- k. Using a #3 Phillips Screwdriver, hold the Screw steady while aligning the Pin in the Cam Lever. It may be necessary to rotate the Pin inside the Cam Lever so that the threaded hole aligns with the Screw. Begin tightening the Screw so it catches the Pin. When the Screw engages with the Pin, close the Cam Lever to lock the Depth Collar. Finish tightening the Screw to 60 in-lbs.
- I. Ensure that the Cam Lever is neither too loose nor too tight. If the Cam Lever is too tight, it will be difficult to open or close and the Depth Collar will not move, even when unlocked. If the Cam Lever is too loose, the Depth Collar will not securely hold the Shaft even when locked. If the Depth Collar can be forcibly pushed up or down the Shaft when locked, the Collar is too loose. Recheck the tension of the Screw and tighten or loosen as needed.









ADJUSTING THE STOW LOCK COLLAR TENSION

ADJUSTING THE STOW LOCK COLLAR TENSION

The tension on the Stow Lock Collar is adjustable and can be tightened or loosened as needed. The Stow Lock Collar may wear and loosen over time. If the Stow Lock Collar is no longer securely holding the Shaft when in the locked position, it may be necessary to tighten the Lock Arm on the Collar.

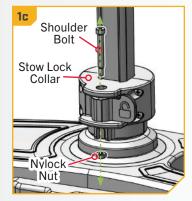
TOOLS AND RESOURCES REQUIRED >

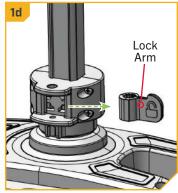
• 1/8" Hex Head Screwdriver

• 3/8" Socket Wrench

INSTALLATION >

- 1
- a. Stow the trolling motor. Ensure that the Lower Unit is resting securely on the Fall Away Ramps.
- b. Unlock the Stow Lock Collar.
- c. Use a 1/8" Hex Head Screwdriver to loosen the Shoulder Bolt and Nylock Nut that secure the Lock Arm to the Stow Lock Collar. Loosen the Bolt in a counterclockwise direction. Remove the Bolt and Nylock Nut and set aside for reassembly later.
- With the Bolt removed, pull the Lock Arm out of the Stow Lock Collar. The tension adjustment for the Stow Lock Collar is made using the Lock Arm.

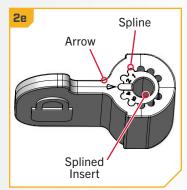


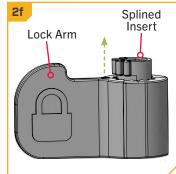


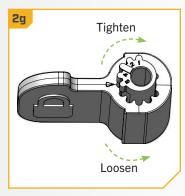
ADJUSTING THE STOW LOCK COLLAR TENSION

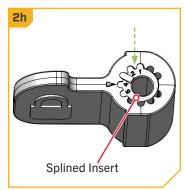
2

- e. Molded into the plastic on top of the Lock Arm is a small arrow. The arrow points to a Splined Insert contained within the Lock Arm. The larger the number in front of the arrow, the higher the tension on the Stow Lock Collar. The Splined Insert within the Lock Arm contains five Splines that are used to adjust the tension. The Stow Lock Collar comes from the factory with the middle Spline aligned to the arrow.
- f. Lift the Splined Insert from the center of the Lock Arm so the Splines are raised and free to rotate.
- g. To tighten the Lock Arm on the Stow Lock Collar, rotate the Splined Insert one Spline clockwise. To loosen the grip of the Lock Arm, rotate the Insert one Spline counterclockwise. A smaller number will be looser, a larger number will be tighter.
- h. When the desired Spline tension is in line with the arrow, press the Splined Insert back into the Lock Arm so that the Insert is fully seated.



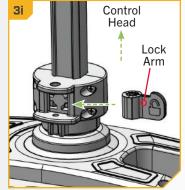


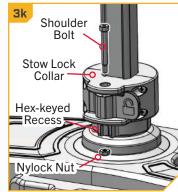


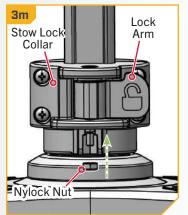


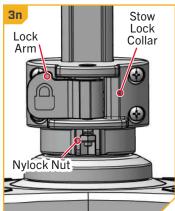
ADJUSTING THE STOW LOCK COLLAR TENSION

- To reassemble, hold the Lock Arm so that the Splined Insert faces the Control Head.
- j. Align the hole in the Lock Arm with the holes in the base of the Stow Lock Collar. Hold the Lock Arm so it is in the unlocked position.
- k. Insert the Shoulder Bolt into the Stow Lock Collar so it passes through the Lock Arm and out the hexkeyed recess.
- I. Insert the Nylock Nut into the hex-keyed recess. The flat side of the Nylock Nut should face toward the Control Head, while the rounded edge should face down.
- m. With a 1/8" Hex Bit Screwdriver and 3/8" Socket Wrench, hand-tighten the Shoulder Bolt. The Nylock Nut should sit flat when tight and be snug with the plastic of the Stow Lock Collar. Threads should stick out slightly and be visible past the end of the Nylock Nut.
- n. Close the Lock Arm on the Stow Lock Collar so that it is in the locked position. Test the security of the Stow Lock Collar by pressing the Stow Deploy Lever to release the Fall Away Ramps, then trying to push the Lower Unit out horizontally and away from the Ramps. If the motor holds successfully, the adjustment is complete. If the motor moves when pushed, pull the Lower Unit back onto the Fall Away Ramps. Remove the Lock Arm and turn the Splined Insert clockwise an additional Spline, Reassemble the Stow Lock Collar and repeat the test until the motor can no longer be moved when the Stow Lock Collar is in the locked \bigcirc position.









NOTICE: If the Stow Lock Collar is too tight, the Shaft will not move freely even when the Stow Lock Collar is unlocked. If the Stow Lock Collar is too loose, it will not securely hold the Shaft when locked.

INSTALLING AN EXTERNAL TRANSDUCER

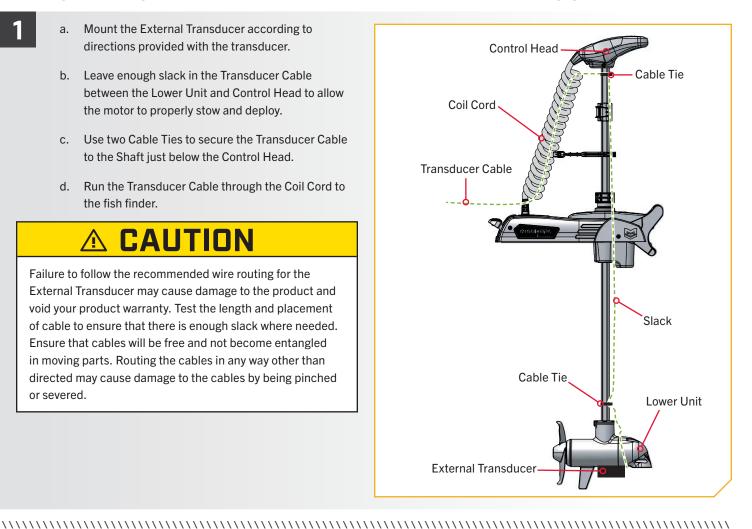
INSTALLING AN EXTERNAL TRANSDUCER

An external transducer is not included with your trolling motor. An external transducer can be installed onto motors that have Advanced GPS Navigation. Installing an external transducer is not recommended for motors with Built-in MEGA Imaging.

- a. Mount the External Transducer according to directions provided with the transducer.
- b. Leave enough slack in the Transducer Cable between the Lower Unit and Control Head to allow the motor to properly stow and deploy.
- c. Use two Cable Ties to secure the Transducer Cable to the Shaft just below the Control Head.
- d. Run the Transducer Cable through the Coil Cord to the fish finder.

CAUTION

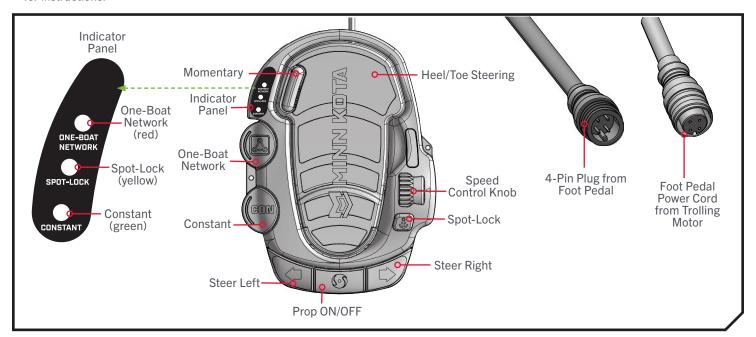
Failure to follow the recommended wire routing for the External Transducer may cause damage to the product and void your product warranty. Test the length and placement of cable to ensure that there is enough slack where needed. Ensure that cables will be free and not become entangled in moving parts. Routing the cables in any way other than directed may cause damage to the cables by being pinched or severed.



USING THE FOOT PEDAL

CONTROLLING SPEED & STEERING WITH THE FOOT PEDAL

The Foot Pedal is used to operate the Terrova QUEST trolling motor. The controls on the Foot Pedal are easy to use. The motor can also be controlled by the Advanced GPS Navigation Wireless Remote or One-Boat Network app. Refer to the associated accessory manual for instructions.



FOOT PEDAL OPERATION

Motor Speed

The Speed Control Knob is located on the right side of the Foot Pedal, above the Spot-Lock button. Turn the Speed Control Knob forward to increase speed and backward to decrease speed. The Speed Control Knob can be set in a range from 0 to 10. Speed can also be adjusted using the Wireless Remote or One-Boat Network app.

△ WARNING

Practice proper ergonomics when operating the foot pedal to prevent injury.

> Heel/Toe Steering

Push the Toe End of the Foot Pedal down to turn right and push the Heel End down to turn left. The position and direction of the Control Head directly corresponds to the position of the motor. Use a foot on the Foot Pedal to control the steering direction during manual operation. The direction of the motor can also be controlled with the Wireless Remote or One-Boat Network app.

> Steer Right/Steer Left

The Steer Right \triangleright and Steer Left \triangleleft buttons are located at the bottom of the Foot Pedal. They function to steer the motor to the right and left. Holding the Steer Right or Steer Left buttons down will continue to steer the motor to the left or right. Small steering changes of less than one degree can be made by quickly tapping the Steer Right and Steer Left buttons.

⚠ WARNING

You are responsible for the safe and prudent operation of your vessel. We have designed the Foot Pedal to be an accurate and reliable tool that will enhance boat operation and improve your ability to catch fish. This product does not relieve you from the responsibility for the safe operation of your boat. You must avoid hazards to navigation and always maintain a permanent watch so you can respond to situations as they develop. You must always be prepared to regain manual control of your boat. Learn to operate your foot pedal and trolling motor in an area free from hazards and obstacles.

Prop ON/OFF

The Prop ON/OFF 69 button is located at the bottom of the Foot Pedal. It functions to momentarily turn the Prop on and off. The Prop will turn on when pressure is applied to the button and turn off when pressure is removed. The Prop ON/OFF button does not change the behavior of the Prop when the Constant button is engaged.

Constant

The Constant @ON button is located on the left side of the Foot Pedal, below the One-Boat Network button. It toggles the motor between Constant motor operation and Momentary motor operation. The green CONSTANT ____ LED on the Indicator Panel will be illuminated when the motor is in Constant motor operation. In Constant motor operation, the Prop will continually run at the speed set by the Speed Control Knob, Wireless Remote, or One-Boat Network app, regardless of whether force is being applied to the Momentary button or Prop ON/OFF button.

Momentary

In Momentary motor operation, the Prop will only run while downward force is applied to the Momentary button. The Momentary button is on the Toe End of the Foot Pedal. Applying downward pressure to the Momentary button will turn the Prop

NOTICE: The motor will not auto correct to drive straight when it encounters an obstruction.

"on." The motor will then run at the speed set by the Speed Control Knob, Wireless Remote, or One-Boat Network app. Removing downward force from the Momentary button will turn the Prop "off." No indicator light is associated with the Momentary button. The Momentary button functions similarly to the Prop ON/OFF button.

CAUTION

If the Prop encounters an obstruction while in Constant or Momentary motor operation, while the Prop is running, the increased electrical current generated by the obstruction will signal the motor to decrease power to the Prop in order to prevent damage.

FOOT PEDAL OPERATION

Spot-Lock

The Spot-Lock 👶 button is located on the bottom-right side of the Foot Pedal and is labeled with an anchor symbol. When the Spot-Lock button is pressed, the location of the motor is recorded to a temporary Spot-Lock location. To engage Spot-Lock, press the Spot-Lock button. To disengage, press the Spot-Lock button again. The yellow SPOT-LOCK LED on the Indicator Panel is illuminated when

Spot-Lock is engaged. Spot-Lock can also be controlled with the Wireless Remote or One-Boat Network app.

When engaging Spot-Lock, a tone will be emitted from the Control Head. When disengaging Spot-Lock with the Spot-Lock button, no tone will be emitted. Steering the motor or adjusting the motor speed will cancel Spot-Lock, and tone consisting of several short beeps will be emitted from the Control Head.

NOTICE: In the default Audio Mode, a tone is emitted from the Control Head when Spot-Lock is engaged. If the Audio Mode is set to Alarm Only, a tone will not be emitted when engaging Spot-Lock. To learn more about Audio Modes, refer to the Wireless Remote Owner's Manual online at minnkota.johnsonoutdoors.com.

One-Boat Network

The One-Boat Network (OBN) & button is located on the left side of the Foot Pedal, below the Indicator Panel. It is a customizable button that may change functions based on user selection. Pressing the OBN button will activate the assigned OBN function. The red One-Boat Network LED on the Indicator Panel is illuminated when this feature is engaged. Each function has a different LED pattern. AutoPilot is the default OBN function. Review the "One-Boat Network" section of this manual to learn more about customizing the OBN button.

NOTICE: Refer to the "One-Boat Network" section of these instructions to learn how to customize the function of the One-Boat Network button on the Foot Pedal.

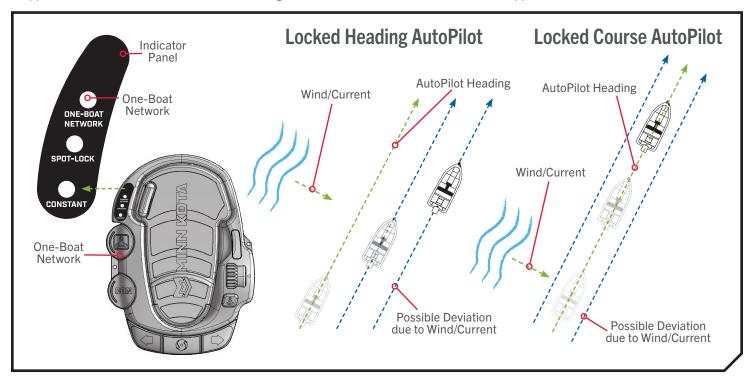
AUTOPILOT

AUTOPILOT AND THE ONE-BOAT NETWORK

AutoPilot on the Advanced GPS Navigation System uses an internal compass to keep the trolling motor pointed in the same compass direction. If the One-Boat Network (OBN) & button on the Foot Pedal is customized to the AutoPilot function, the button will engage and disengage AutoPilot.

AUTOPILOT MODES

Two different modes of AutoPilot are available: Locked Heading AutoPilot and Locked Course AutoPilot. Both are collectively referred to as AutoPilot. There are distinct differences between the two AutoPilot Modes and how they control the boat. Both Locked Heading and Locked Course AutoPilot are valuable tools anglers can use for accurate and precise bait presentation. Minn Kota highly recommends getting on the water and trying both Locked Heading AutoPilot and Locked Course AutoPilot in various fishing situations and applications. The AutoPilot mode can be set using the Wireless Remote or One-Boat Network app.



Locked Heading AutoPilot

AutoPilot uses an internal compass to provide heading lock. When Locked Heading AutoPilot is on, it keeps the motor pointed in the same compass direction. If a manual steering correction is made, Locked Heading AutoPilot locks onto the new compass heading to which the boat was steered. This method of heading tracking does not take into account external forces such as a side wind or currents, which can allow side drift.

Locked Course AutoPilot

Locked Course AutoPilot uses not only compass heading but also GPS data to correct for crosswinds, currents, and other external forces to keep the boat on the intended course. When Locked Course AutoPilot is turned on, it creates a course that the trolling motor will follow. When the user steers to a new heading, a new course is created. Locked Course AutoPilot will keep the boat on the course in most conditions. When very extreme conditions exist, such as very strong winds or currents, the trolling motor may not have enough power to control the boat smoothly. In these extreme cases, it may be best to use Locked Heading AutoPilot and let the boat move with the wind or current if the motor is not powerful enough to overcome it.

△ CAUTION

This unit uses a magnetic compass to detect the direction of travel. The compass can be adversely affected by magnets or large, ferrous metal objects near (within 12" of) the trolling motor control head.

Obstructions on the Prop may cause excessive vibration of the motor control head. This vibration can cause the compass to wander and erratic steering to occur. Clear the obstruction to return the motor to normal operation.

The trolling motor has automatic steering shutdown for safety. In conditions where an obstruction prevents the trolling motor from turning, or in extremely windy conditions, the automatic steering may stop. Any steering input will reset the system to normal.

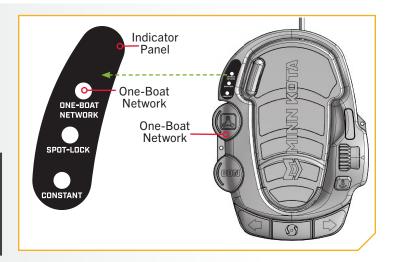
> Toggle AutoPilot On/Off

1

- a. While the motor is running, AutoPilot can be turned on by pressing the One-Boat Network & button located on the Foot Pedal.
- b. The red One-Boat Network LED on the Indicator Panel will illuminate when AutoPilot is engaged. While AutoPilot is on, steer the trolling motor as desired.

NOTICE: After steering to a new direction, there is a short delay before the direction is locked in to allow the compass to stabilize. When broad speed changes are made, the AutoPilot heading may change slightly. This is normal.

c. To turn AutoPilot "off," press the One-Boat Network & button.



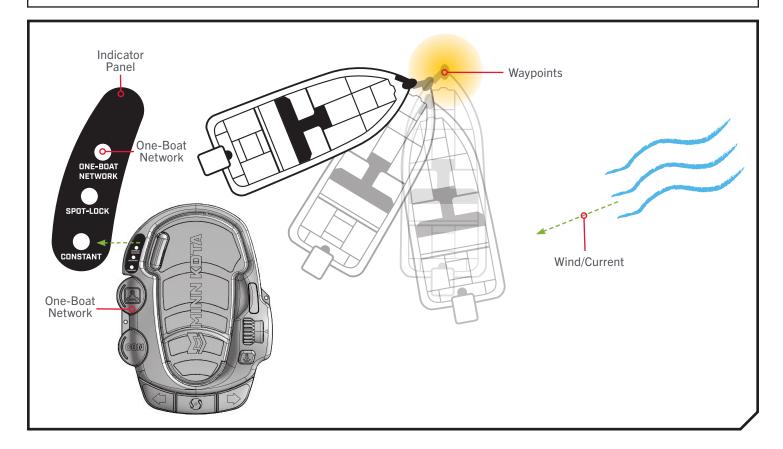
WAYPOINTS

WAYPOINTS AND THE ONE-BOAT NETWORK

Waypoints are saved latitude/longitude positions. They mark a position of interest, such as favorite fishing areas, structures, or marker buoys. Waypoints work similarly to Spot-Locks. If the One-Boat Network (OBN) & button on the Foot Pedal is customized to the Waypoint function, the button will mark Waypoints in the Advanced GPS Navigation System when pressed. For more information on working with Waypoints, please see the Advanced GPS Navigation System or Humminbird owner's manual.

▲ WARNING

Watch for a turning Prop when working with Waypoints. Auto Prop On is set to "off" by default on the Advanced GPS Navigation System. If Auto Prop On is turned "on," the Prop will automatically turn on when a Waypoint is engaged, even if the engagement is accidental. A turning Prop can cause injury. If Auto Prop On is turned "off," the Prop must be enabled before the boat will begin navigating to a Waypoint.

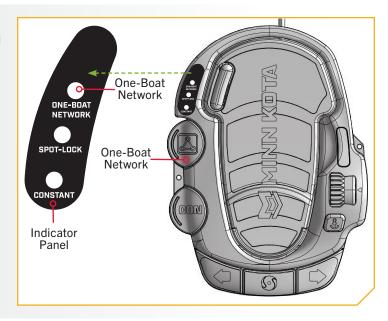


WAYPOINTS

Mark a Waypoint



a. While the trolling motor is running, mark a Waypoint by pressing the One-Boat Network & button. The red One-Boat Network LED on the Indicator Panel will briefly illuminate and then turn off to indicate a Waypoint is marked.



SHALLOW WATER ANCHOR

SHALLOW WATER ANCHOR CONTROL AND THE ONE-BOAT NETWORK

The One-Boat Network allows for control of a Shallow Water Anchor (SWA) when one is paired with the Advanced GPS Navigation Bluetooth Network. SWAs that can pair with the Advanced GPS Navigation system include the Minn Kota Bluetooth enabled Raptor and Talon. For more information on how to pair the SWA with the Advanced GPS Navigation system, please see the SWA owner's manual.

When two Raptors are paired together or two Talons are paired together, the anchor selected and controlled by the Foot Pedal can be Port, Starboard or both. To change the selection of which anchor is selected, use the remote or app paired to the Shallow Water Anchor.

⚠ WARNING

Be sure that the Raptor/Talon is clear of obstructions and persons while deploying or retracting. Take care that neither you nor other persons approach the Raptor/Talon too closely while operating, neither with body parts nor with objects. The Raptor/Talon is powerful and may endanger or injure you or others. While the Raptor/Talon is operating, watch out for persons swimming and for floating objects. Persons who lack the ability to run the Raptor/Talon or whose reactions are impaired by alcohol, drugs, medication, or other substances are not permitted to use this product.

△ CAUTION

The Talon is equipped with a Deployment Notification Alarm. The Alarm is needed to comply with warranty requirements and when properly installed the alarm will only sound when the ignition key is turned on when the Talon is not fully retracted. Boat control may be affected by a deployed Talon. Take note of the Alarm, and always watch to make sure that the Talon is fully retracted while the boat is operating.

△ CAUTION

The spaces between the Outer Arm, Inner Arm, Spike and brackets of the Raptor can create a pinch point. Do not come in contact with an area of the Raptor that may cause a pinch point while it is moving in any direction to avoid the risk.

SHALLOW WATER ANCHOR

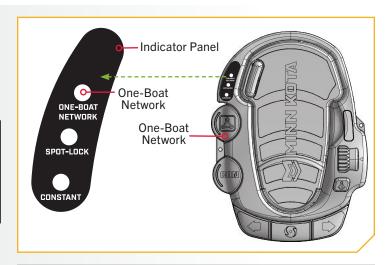
Deploy the Shallow Water Anchor

- 1
- a. Check to make sure that the Shallow Water Anchor (Raptor/Talon) is powered "on" and paired to the trolling motor.

b. Locate the One-Boat Network & button on the Foot Pedal and double-press it to deploy the Raptor/Talon.

NOTICE: The One-Boat Network button does not need to be held in to keep the Raptor/Talon deploying. The Raptor/Talon will automatically continue to deploy when the button is double-pressed until it has reached its full deployment, received input to stop, or anchors.

c. The red One-Boat Network LED on the Indicator Panel will steadily flash when the anchor is deploying and stay on when the anchor is at any state of deployment.



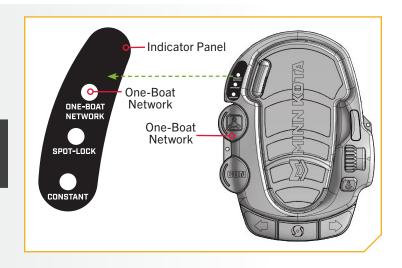
NOTICE: While the Raptor/Talon is deploying, the action can be paused by pressing the One-Boat Network button on the Foot Pedal.

Retract the Shallow Water Anchor

- 1
- a. Check to make sure that the Shallow Water Anchor (Raptor/Talon) is powered "on" and paired to the trolling motor.
- b. Locate the One-Boat Network & button on the Foot Pedal and press it to retract the Raptor/Talon.

NOTICE: While the Raptor/Talon is retracting, the action can be paused by pressing the One-Boat Network button on the Foot Pedal.

c. The red One-Boat Network LED on the Indicator Panel will steadily flash when the anchor is retracting and stay on when the anchor is at any state of deployment.



SPOT-LOCK

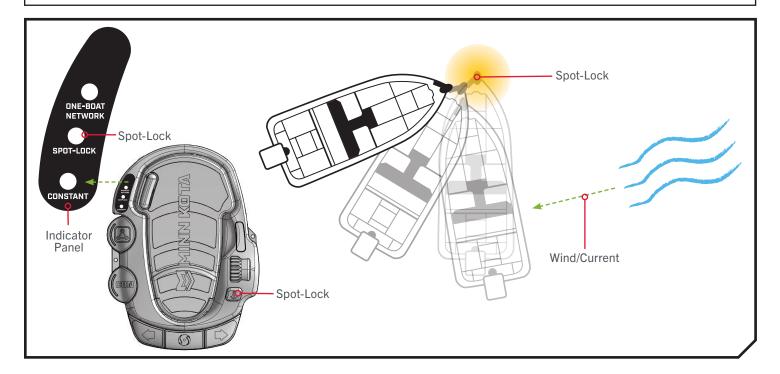
HOW SPOT-LOCK WORKS

Spot-Lock uses a single point of reference that is recorded when the Spot-Lock & button is pressed. The reference point is a set of GPS coordinates captured at the location of the trolling motor at the moment the button is pressed. This point is recorded and can be saved into one of the Spot-Lock memory locations. Spot-Lock works by recognizing the GPS coordinates and will automatically navigate the boat to keep it at the Spot-Lock location. If the motor recognizes it is not positioned at the Spot-Lock location, it will control motor speed and direction in an attempt to keep the motor on the Spot-Lock. For more specific instructions on using Spot-Lock, refer to the Wireless Remote owner's manual online at minnkota.johnsonoutdoors.com.

NOTICE: Spot-Lock is based on the location of the trolling motor, not on the location or direction of the boat. Outside forces such as wind and current will cause the boat to move. Spot-Lock will navigate to maintain the motor on the Spot-Lock location, regardless of the position of the boat.

▲ WARNING

Watch for a turning Prop when working with Spot-Lock. The Prop will automatically turn on when Spot-Lock is engaged, even if the engagement is accidental. A turning Prop can cause injury. The Prop will turn "on" for Spot-Lock, regardless of the Prop Auto On setting used on the other control methods in the Advanced GPS Navigation System.



> Toggle Spot-Lock On/Off

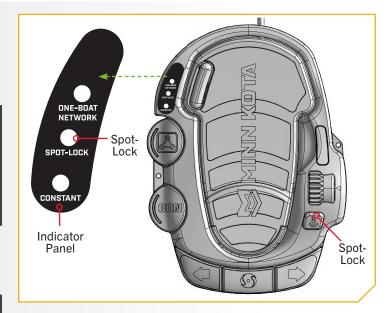
1

a. While the motor is running, Spot-Lock can be turned on by pressing the Spot-Lock button located on the Foot Pedal. The yellow SPOT-LOCK LED on the Indicator Panel will illuminate when Spot-Lock is engaged.

NOTICE: In the default Audio Mode, a tone is emitted from the Control Head when Spot-Lock is engaged. If the Audio Mode is set to Alarm Only, a tone will not be emitted when engaging Spot-Lock. To learn more about Audio Modes, refer to the Wireless Remote owner's manual online at minnkota.johnsonoutdoors.com.

b. To disengage Spot-Lock, press the Spot-Lock button again or press any button on the Foot Pedal to manually steer the trolling motor.

NOTICE: Adjusting the Prop speed or manually steering the motor will disengage Spot-Lock, and a tone consisting of several short beeps will emit from the Control Head. Manually steering or adjusting the Prop speed with the Wireless Remote or One-Boat Network app will also cancel Spot-Lock.



NOTICE: If the Spot-Lock button is accidentally pressed, press the Spot-Lock button again to cancel Spot-Lock.

SERVICE & MAINTENANCE

PROP REPLACEMENT

TOOLS AND RESOURCES REQUIRED >

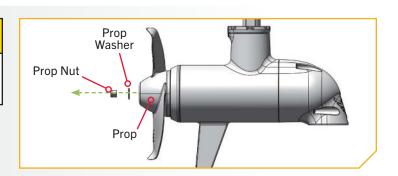
• 9/16" Deep Well Socket

INSTALLATION >

⚠ CAUTION

Disconnect the motor from all sources of power before beginning any prop work or maintenance.

- a. Hold the Prop and loosen the Prop Nut with a 9/16" Deep Well Socket.
- b. Remove the Prop Nut and Prop Washer.

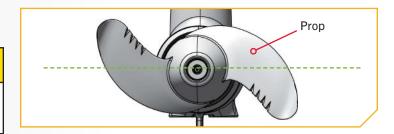


NOTICE: If the Drive Pin is sheared or broken, hold the Armature Shaft stationary with a Flat-Blade Screwdriver by pressing into the slot on the end of the shaft while loosening the Prop Nut.

Turn the old Prop so it is horizontal and pull it straight off. If the Drive Pin falls out, push it back in.

CAUTION

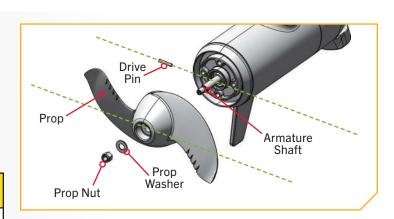
If the Prop does not readily slide off, take care not to bend the Armature Shaft. Pull the Prop evenly off the Armature Shaft.



- d. Align the new Prop so it is horizontal and parallel with the Drive Pin. Slide the Prop onto the Armature Shaft and Drive Pin until it is seated against the lower unit.
- e. Reinstall the Prop Washer and Prop Nut onto the end of the Armature Shaft. While holding the Prop horizontal, tighten the Prop Nut with a 9/16" Deep Well Socket. Tighten the Prop Nut to 25-35 in-lbs.



Do not over-tighten as this can damage the Prop.



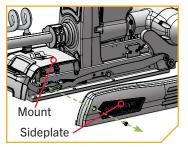
GENERAL MAINTENANCE

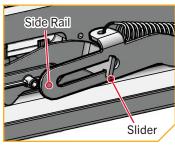
GENERAL MAINTENANCE

- After use, the entire motor should be rinsed with freshwater. This series of motor is not equipped for saltwater exposure.
- The composite shaft requires periodic cleaning and lubrication for proper retraction and deployment. A coating of an aqueous-based silicone spray will improve operation.

- The Prop must be inspected and cleaned of weeds and fishing line after every use. Fishing line and weeds can get behind the Prop, damage the seals and allow water to enter the motor.
- Verify that the Prop Nut is secure each time the motor is used.
- The Prop is designed to provide operation with very high efficiency. The leading edge of the blades must be kept smooth to maintain top performance of the Prop. If the edges are rough or nicked from use, restore them to smoothness by sanding them with fine sandpaper.
- To prevent accidental damage during transportation or storage, disconnect the battery whenever the motor is off of the water. For prolonged storage, lightly coat all metal parts with an aqueous-based silicone spray.
- When using lithium batteries, it is best to charge them right before using them. Storing lithium batteries in a fully charged state for long periods of time may cause damage to the batteries. Check with the battery manufacturer for specifics on the battery.
- For maximum battery life of all other batteries except lithium, recharge the battery(s) as soon as possible after use. For maximum motor performance, restore the battery to full charge prior to use. Check with the battery manufacturer for specifics on the battery.
- Keep battery terminals clean with fine sandpaper or emery cloth.
- Keep the Foot Pedal well dry and clean. Debris that gets in the Foot Pedal can cause interference of pedal operation. It is recommended to use compressed air to clean the Foot Pedal after each use.
- Stow the motor after each use to allow water to drain from the Steering Housing. Water that sits in the steering housing when the motor is not in use may cause damage.
- When the motor is deployed, periodically check that the area between the Mount and Steering Housing is clean and free of debris. The Mount contains pads that contact the Steering Housing when stowed. If debris such as dirt, gravel, weeds, or fishing line enters this space, it may create an obstruction on the pads and prevent a secure stow. Periodically clean this space to ensure a secure stow.

- Periodically check the Side Rails on the Mount for debris. Remove
 the left and right Sideplates using a #3 Phillips Screwdriver to
 access the Side Rails. Clear any dirt or debris around the Slider,
 then apply a water-based lubricant to the Slider. Grease the Slider
 on both the right and left sides of the Mount.
- Periodically check the motor for loose hardware and damaged components.





TROUBLESHOOTING

- 1. Motor fails to run or lacks power:
 - Check the state of the batteries and replace if necessary. Low battery voltage will cause an error.
 - Check battery connections for proper polarity.
 - Make sure terminals are clean and corrosion-free. Use fine sandpaper or emery cloth to clean terminals.
 - Check battery water level. Add water if needed.
- 2. Motor loses power after a short running time:
 - Check battery charge. If low, restore to full charge.
- 3. Motor is difficult to stow:
 - Lubricate the composite shaft.
 - For 72" shaft motors, check that the Stow Lock Collar is in the unlocked position. If difficult to stow even when unlocked, loosen the tension on the Stow Lock Collar.

- 4. You experience Prop vibration during normal operation:
 - Replace the Prop.
 - Remove and rotate the Prop 180°. See removal instructions in the Prop Replacement section.
- 5. Experiencing interference with your fish finder:
 - You may, in some applications, experience interference in your fish finder display. We recommend that you use a separate deep cycle marine battery system for your trolling motor. If problems still persist, call our service department at 1-800-227-6433.
- 6. Experiencing flashing red System Status LED on the Indicator Panel:
 - The trolling motor is communicating that there is an error. Check the Wireless Remote Diagnostic menu for an error code, then refer to the Wireless Remote owner's manual for information on error codes and solutions. Correct the error and cycle power to the trolling motor. If the LED continues to flash red, please contact the Minn Kota service department.

NOTICE: For all other malfunctions, visit an Authorized Service Center. You can search for an Authorized Service Center in your area by visiting minnkota.johnsonoutdoors.com, or by calling our customer service number at 800-227-6433.

FOR FURTHER TROUBLESHOOTING AND REPAIR

FOR FURTHER TROUBLESHOOTING AND REPAIR

We offer several options to help you troubleshoot and/or repair your product. Please read through the options listed below.



Buy Parts Online

You can buy parts online directly from our website at minnkota.johnsonoutdoors.com. From screws to sideplates, you can order replacement parts for your Minn Kota products.



Frequently Asked Questions

Find answers to general inquiries, battery and rigging installation, and networking scenarios. We have FAQs available on our website at minnkota.johnsonoutdoors.com to help answer all of your Minn Kota questions.



Call Us (for U.S. and Canada)

Our consumer service representatives are available Monday – Friday between 7:00 a.m. – 4:30 p.m. CST at 800-227-6433. If you are calling to order parts, please have the 11-character serial number from your product, specific part numbers, and credit card information available. This will help expedite your call and allow us to provide you with the best consumer service possible. You can reference the parts list located in your manual to identify the specific part numbers.



Contact Us

You can contact our consumer service department with questions regarding your Minn Kota products. To inquire, visit minnkota.johnsonoutdoors.com.



Authorized Service Centers

Minn Kota has over 800 authorized service centers in the United States and Canada where you can purchase parts or get your products repaired. Please visit our website to locate a service center in your area.



COMPLIANCE STATEMENTS

ENVIRONMENTAL COMPLIANCE STATEMENT

It is the intention of JOME to be a responsible corporate citizen, operating in compliance with known and applicable environmental regulations, and a good neighbor in the communities where we make or sell our products.

WEEE DIRECTIVE

EU Directive 2002/96/EC "Waste of Electrical and Electronic Equipment Directive (WEEE)" impacts most distributors, sellers, and manufacturers of consumer electronics in the European Union. The WEEE Directive requires the producer of consumer electronics to take responsibility for the management of waste from their products to achieve environmentally responsible disposal during the product life cycle.

WEEE compliance may not be required in your location for electrical & electronic equipment (EEE), nor may it be required for EEE designed and intended as fixed or temporary installation in transportation vehicles such as automobiles, aircraft, and boats. In some European Union member states, these vehicles are considered outside of the scope of the Directive, and EEE for those applications can be considered excluded from the WEEE Directive requirement.

This symbol (WEEE wheelie bin) on product indicates the product must not be disposed of with other household refuse. It must be disposed of and collected for recycling and recovery of waste EEE. Johnson Outdoors Inc. will mark all EEE products in accordance with the WEEE Directive. It is our goal to comply in the collection, treatment, recovery, and environmentally sound disposal of those products; however, these requirements do vary within European Union member states. For more information about where you should dispose of your waste equipment for recycling and recovery and/or your European Union member state requirements, please contact your dealer or distributor from which your product was purchased.



DISPOSAL

Minn Kota motors are not subject to the disposal regulations EAG-VO (electric devices directive) that implements the WEEE directive. Nevertheless never dispose of your Minn Kota motor in a garbage bin but at the proper place of collection of your local town council.

Never dispose of battery in a garbage bin. Comply with the disposal directions of the manufacturer or his representative and dispose of them at the proper place of collection of your local town council.

REGULATORY COMPLIANCE INFORMATION

Advanced GPS Navigation

For regulatory information on motors that come factory installed with Advanced GPS Navigation, please refer to the Advanced GPS Navigation Owner's Manual online at minnkota.johnsonoutdoors.com.

> KC Compliance Information

CONTROLLER

R-R-Jom-TERROVAQUEST

REMOTE

R-R-Jom-WIRFI FSSRFMOTF





FCC COMPLIANCE

FCC COMPLIANCE

This device complies with Part 15 of the FCC rules. Operation is subject to the following two conditions:

- 1. This device may not cause harmful interference.
- 2. This device must accept any interference that may be received, including interference that may cause undesired operation.

Changes or modifications not expressly approved by Johnson Outdoors Marine Electronics, Inc. could void the user's authority to operate this equipment.

NOTICE: This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

INDUSTRY CANADA COMPLIANCE

This product meets the applicable Industry Canada technical specifications. Operation is subject to the following two conditions: (1) this device may not cause interference, and (2) this device must accept any interference, including interference that may cause undesired operation of the device.

ENVIRONMENTAL RATINGS

Ambient operating temperature range: -10C to 50C Ambient operating humidity range: 5% to 95% Maximum operating altitude: 10,000 feet

